

リモートセンシングの防災分野への応用

Application of Remote Sensing to Disaster Management

July 5, 2018

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<http://ares.tu.chiba-u.jp/>

Contents

- Remote Sensing and Disaster Management

- Satellite Optical and Thermal Sensors

- Satellite SAR

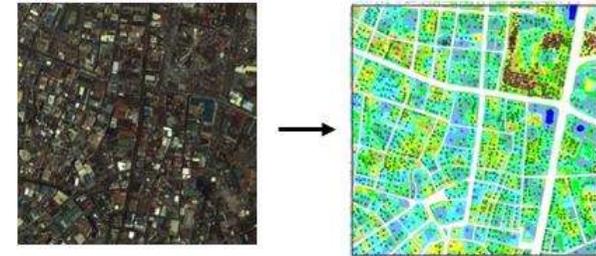
- Airborne SAR

- Lidar and UAV

Objectives of Remote Sensing in Disaster Management

■ Pre-event exposure and topography mapping:

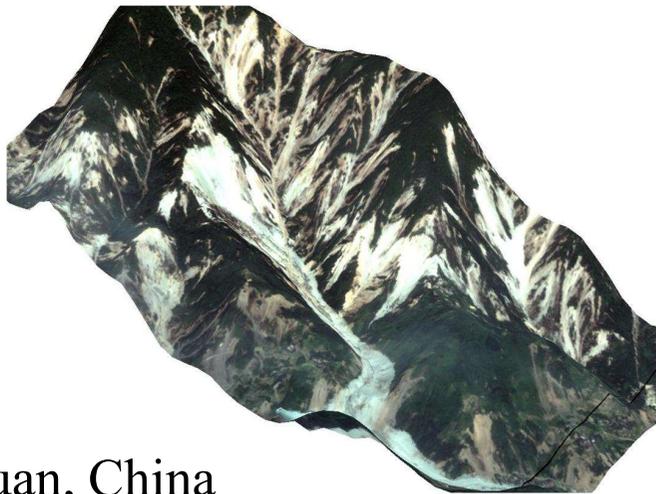
land-cover classification, building and road detection, DSM/DEM, surface temperature



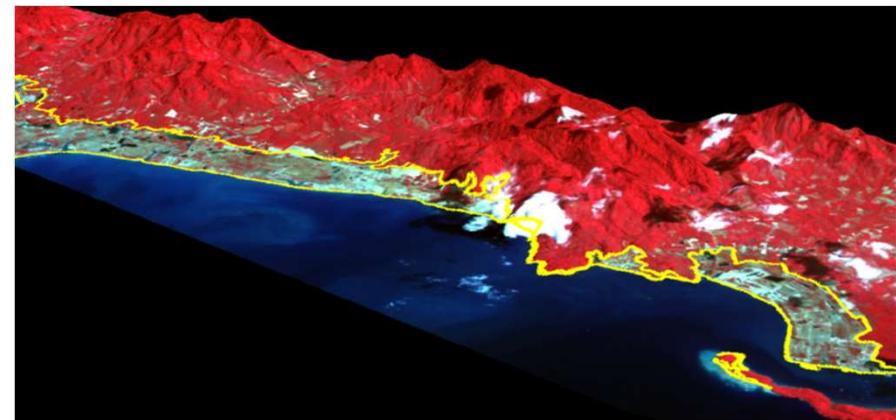
■ Post-event damage assessment:

change detection due to natural and man-made disasters

- *Pre-event use is basically the same as other application fields.*
- *Combined use of **texture** (optical/SAR) and **GIS & DEM** is important for pre- and post-event damage assessment.*



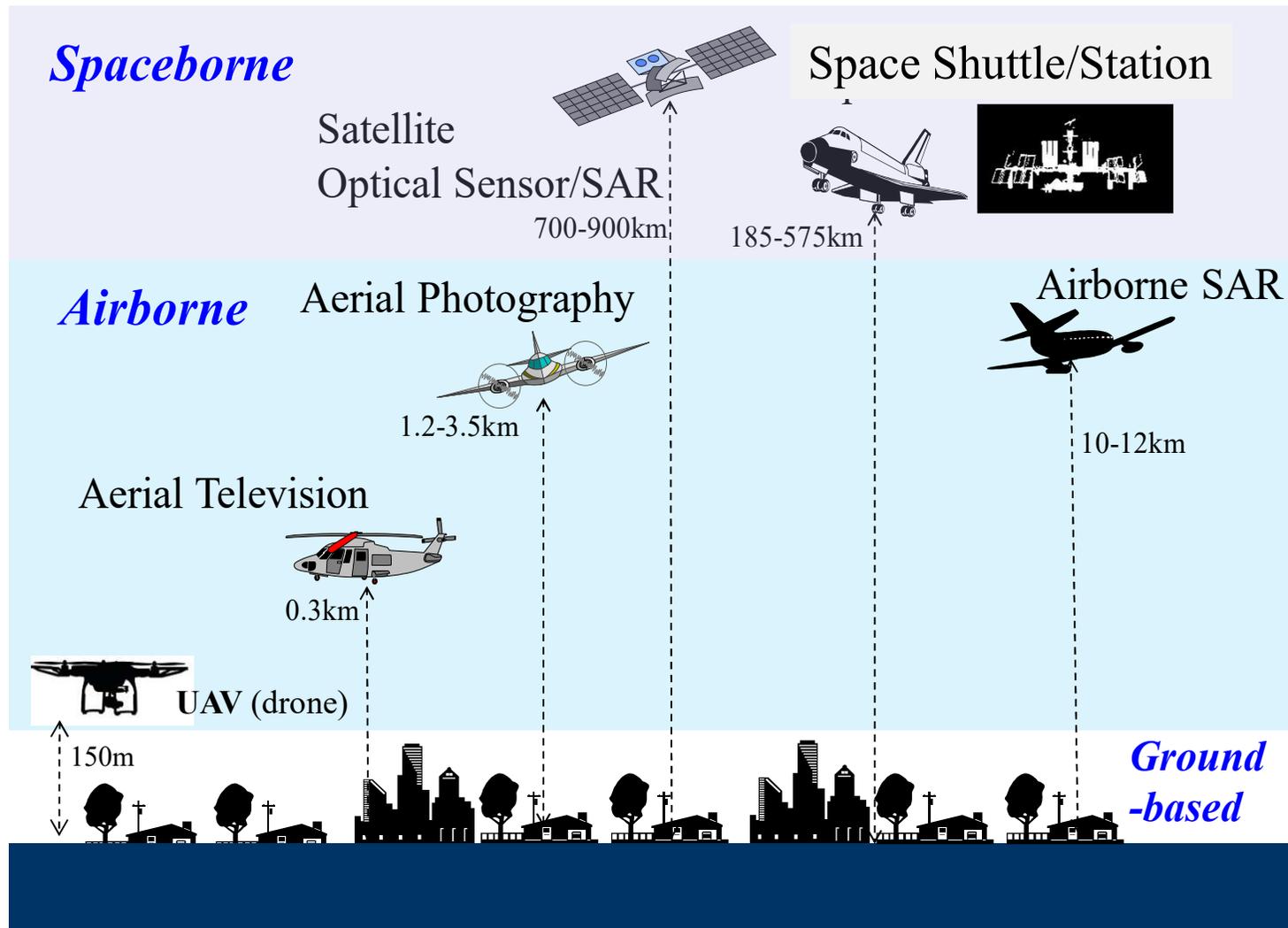
Sichuan, China



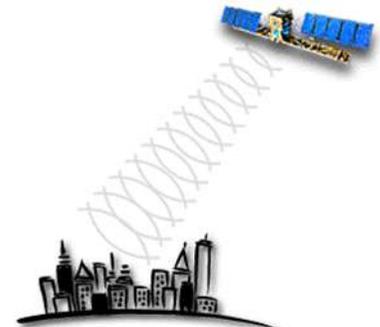
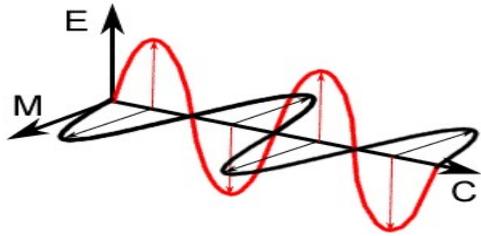
Khao Lak, Thailand

Platforms of Remote Sensing

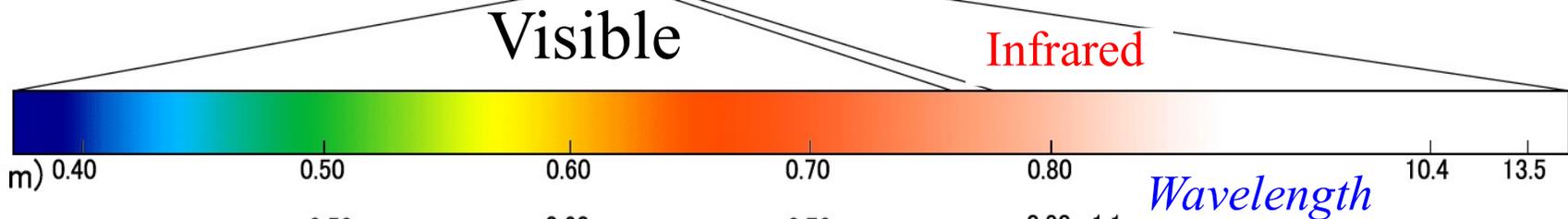
- **Satellite:** near-polar orbit, geo-stationary, Space Shuttle/Station
- **Airborne platform:** airplane, helicopter, drone
- **Ground-based:** balloon, tall building, crane, ladder, car



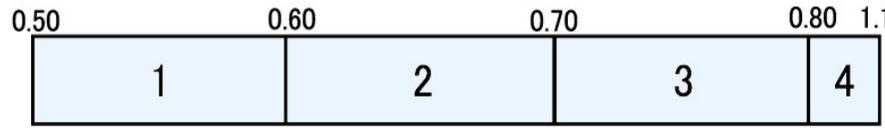
Wavelength of Electromagnetic Waves and Satellite Sensors



Reflection *Radiation* *Active*



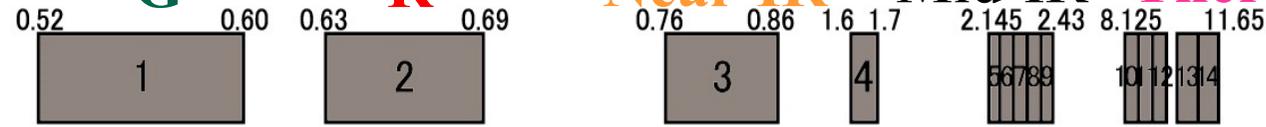
LANDSAT/MSS
空間分解能: 80 m



LANDSAT/TM
空間分解能: 30 m, B6: 120 m



TERRA/ASTER
空間分解能: B1-B3: 15 m, B4-B9: 30 m
B10-B14: 90 m



B **G** **R** **Near-IR** **Mid-IR** **Thermal**

Acquisition condition of various sensors and platforms in disaster response

Platform /Sensor	Satellite ◎ Large coverage	Airborne ○ Mod. coverage	Ground Based △ Low coverage
Optical Sensor	△ Day, Fixed time △ No cloud	○ Day, Any time ○ No low cloud	◎ Day, Any time
LiDAR	△	○ All day, Any time ○ No low cloud ◎ High accuracy	◎ Day, Any time
Thermal Infrared	○ All day , Fixed time △ No cloud △ Low resolution	◎ All day, Any time ○ No low cloud ○ Mod. resolution	◎ All day, Any time ◎ High resolution
SAR	○ All day , Fixed time ◎ All weather	◎ All day, Any time ◎ All weather △ R & D stage	△ Ground penetration Radar

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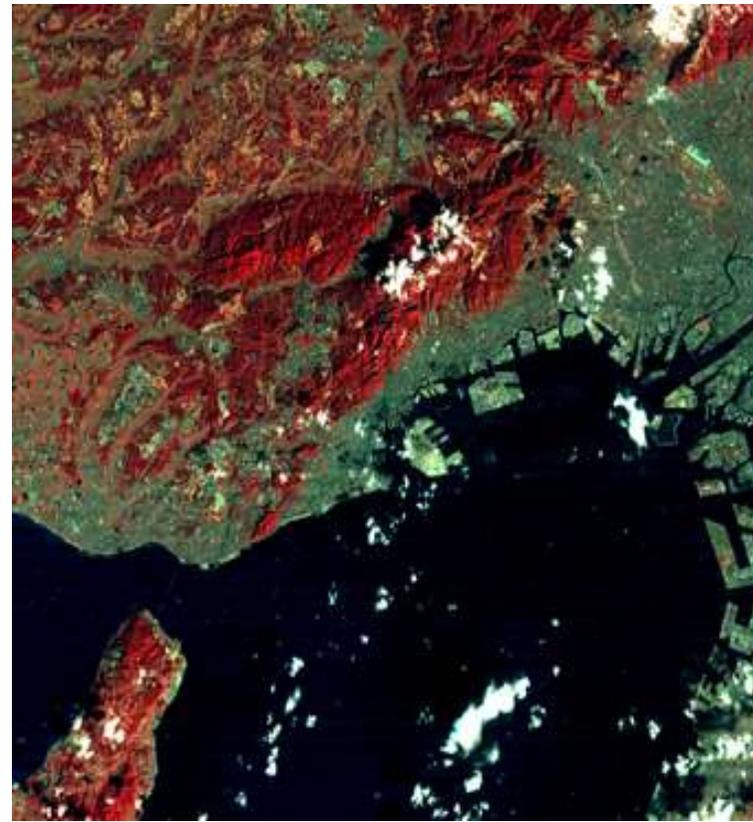
- Airborne SAR

- Lidar and UAV

Landsat-5 TM Images of Kobe area in 1994-95



Aug. 17, 1994 (Before EQ)

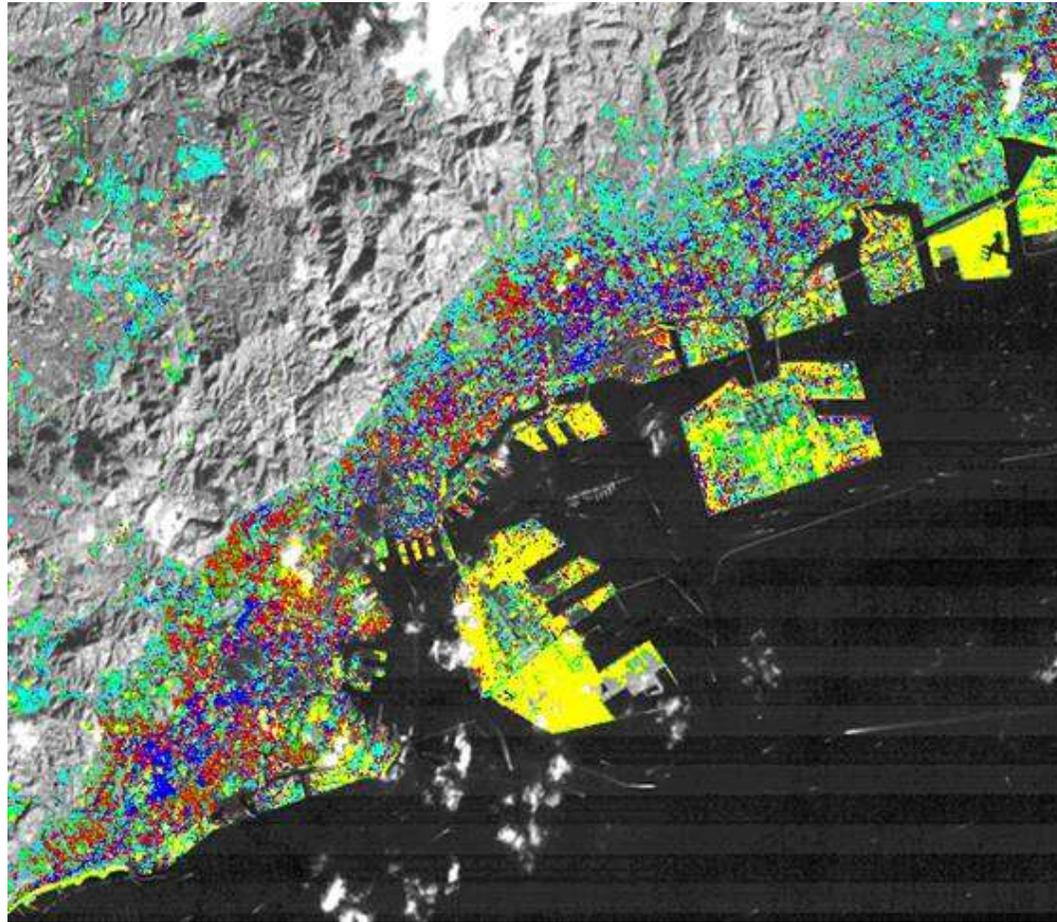


Jan. 24, 1995 (After EQ)



*1998 RIKEN EDM
Disaster Information Systems Team*

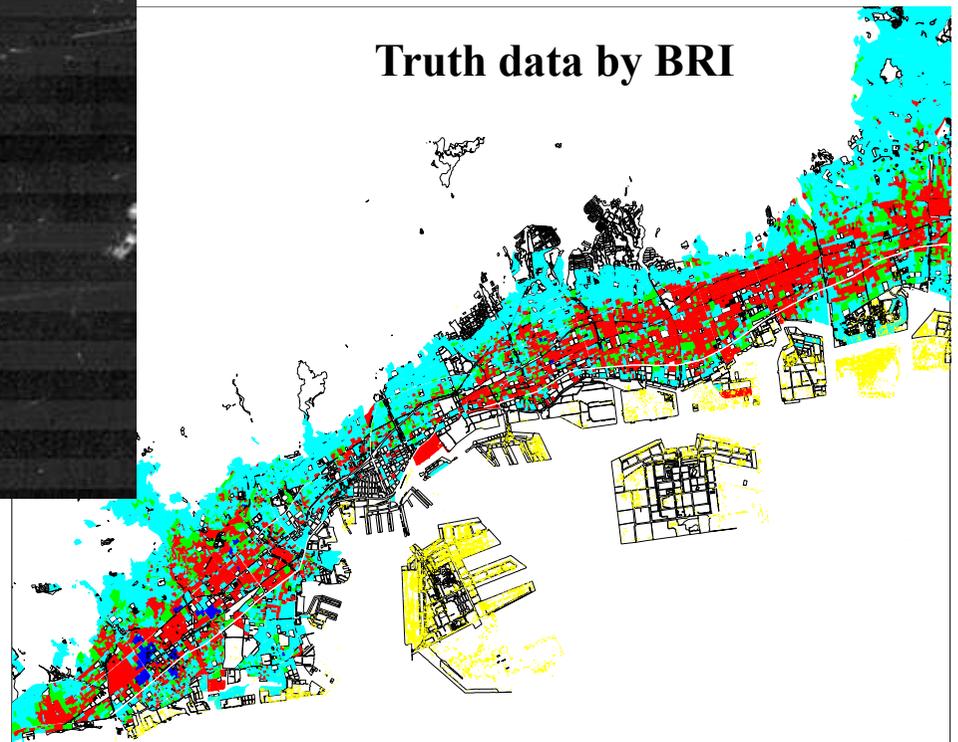
Damage Distribution Estimated from Landsat-5 Images



-  Liquefied Area
-  Burned Area
-  Heavy Damage
-  Slight Damage
-  No Damage

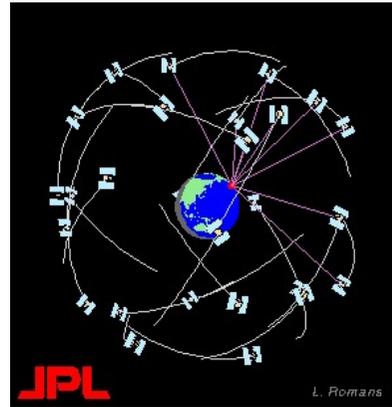
Pre-event: 08/17/94

Post-event: 01/24/95

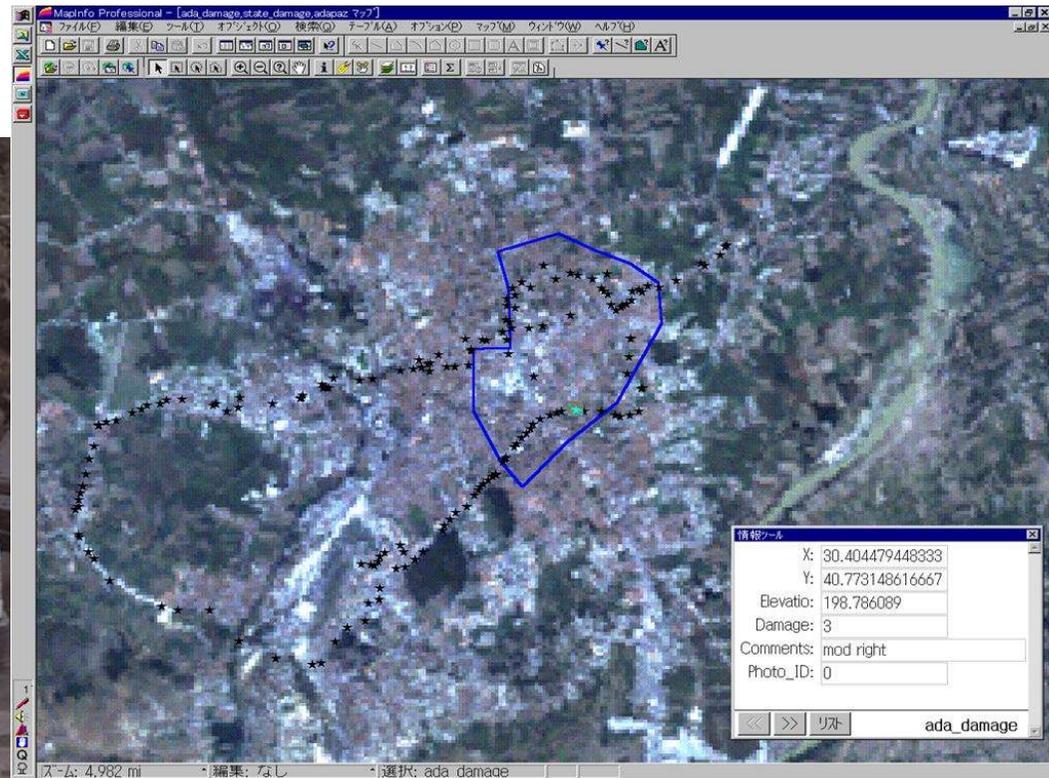


Use of GPS and RS Data for Field Survey

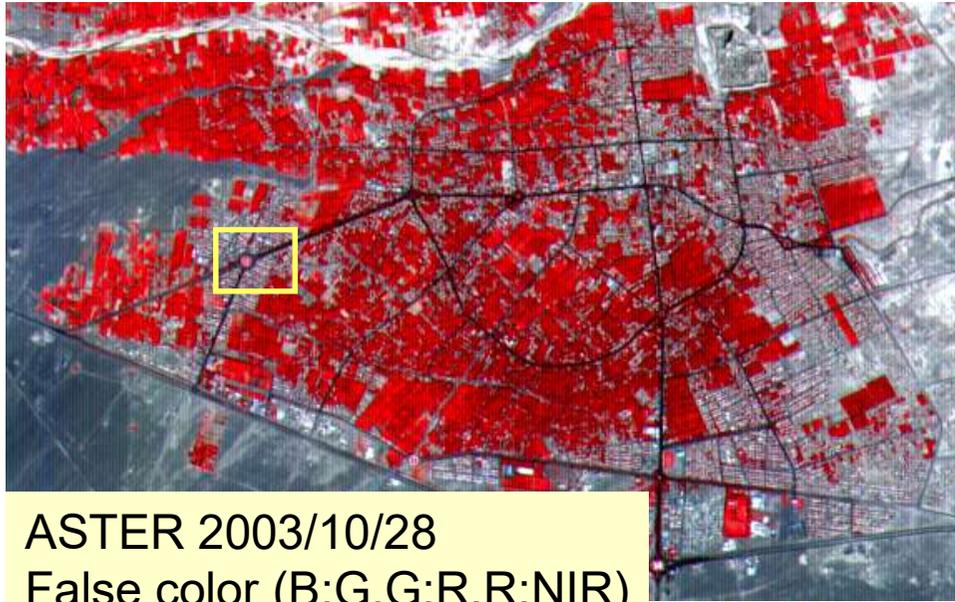
Joint Survey by MCEER/EDM after the 1999 Kocaeli, Turkey EQ



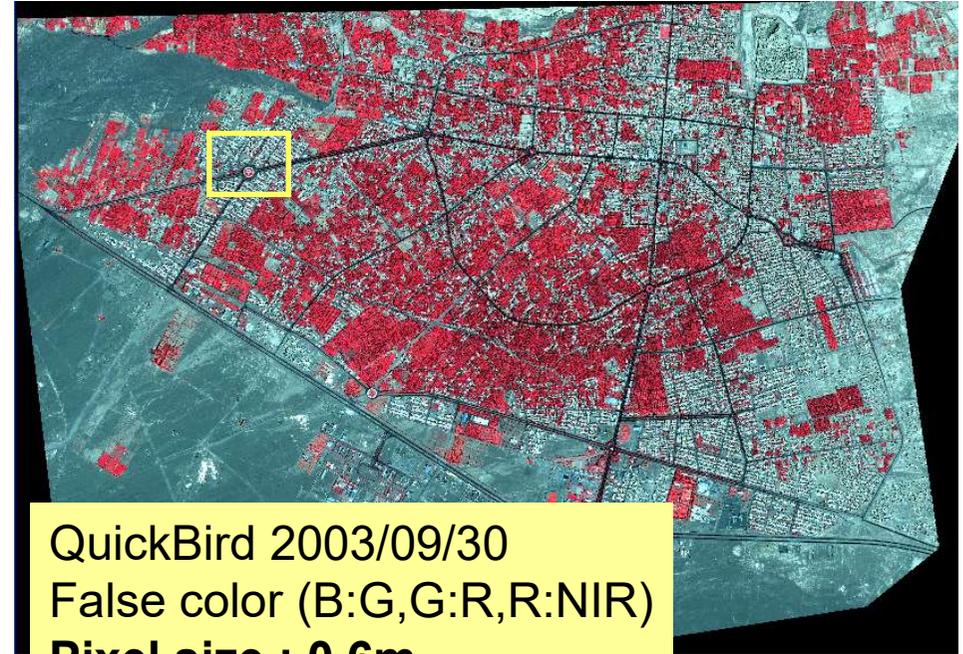
Landsat image
as a base map



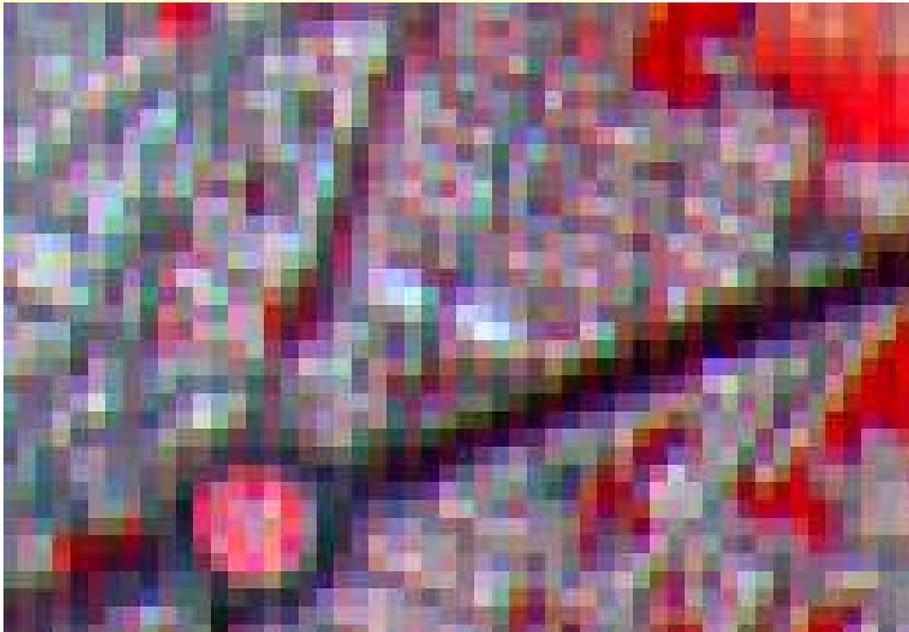
Spatial Resolution: ASTER and QuickBird Images of Bam, Iran



ASTER 2003/10/28
False color (B:G, G:R, R:NIR)
Pixel size : 15m

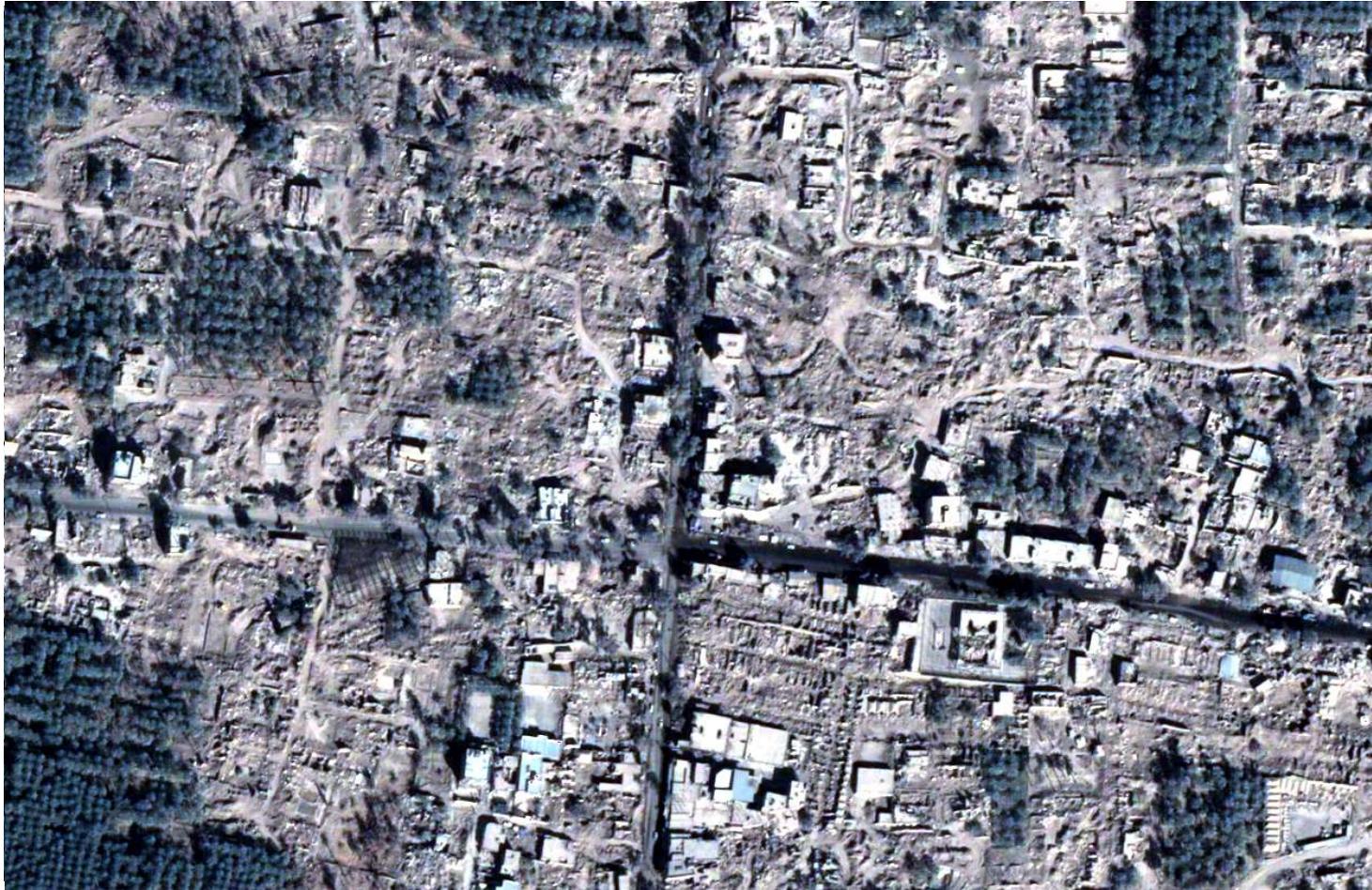


QuickBird 2003/09/30
False color (B:G, G:R, R:NIR)
Pixel size : 0.6m



Change Detection: QB images of Bam, Iran

Pre-event 2003.9.30 → Post-event 2004.1.3



Damage classification of masonry buildings (EMS, 1998) and typical pre- and post event QB images

EMS: *European Macroseismic Scale*

Classification of damage to masonry buildings	
	<p>Grade 1: Negligible to slight damage (no structural damage, slight non-structural damage) Hair-line cracks in very few walls. Fall of small pieces of plaster only. Fall of loose stones from upper parts of buildings in very few cases.</p>
	<p>Grade 2: Moderate damage (slight structural damage, moderate non-structural damage) Cracks in many walls. Fall of fairly large pieces of plaster. Partial collapse of chimneys.</p>
	<p>Grade 3: Substantial to heavy damage (moderate structural damage, heavy non-structural damage) Large and extensive cracks in most walls. Roof tiles detach. Chimneys fracture at the roof line; failure of individual non-structural elements (partitions, gable walls).</p>
	<p>Grade 4: Very heavy damage (heavy structural damage, very heavy non-structural damage) Serious failure of walls; partial structural failure of roofs and floors.</p>
	<p>Grade 5: Destruction (very heavy structural damage) Total or near total collapse.</p>

Pre- event



Post- event



Grade 3

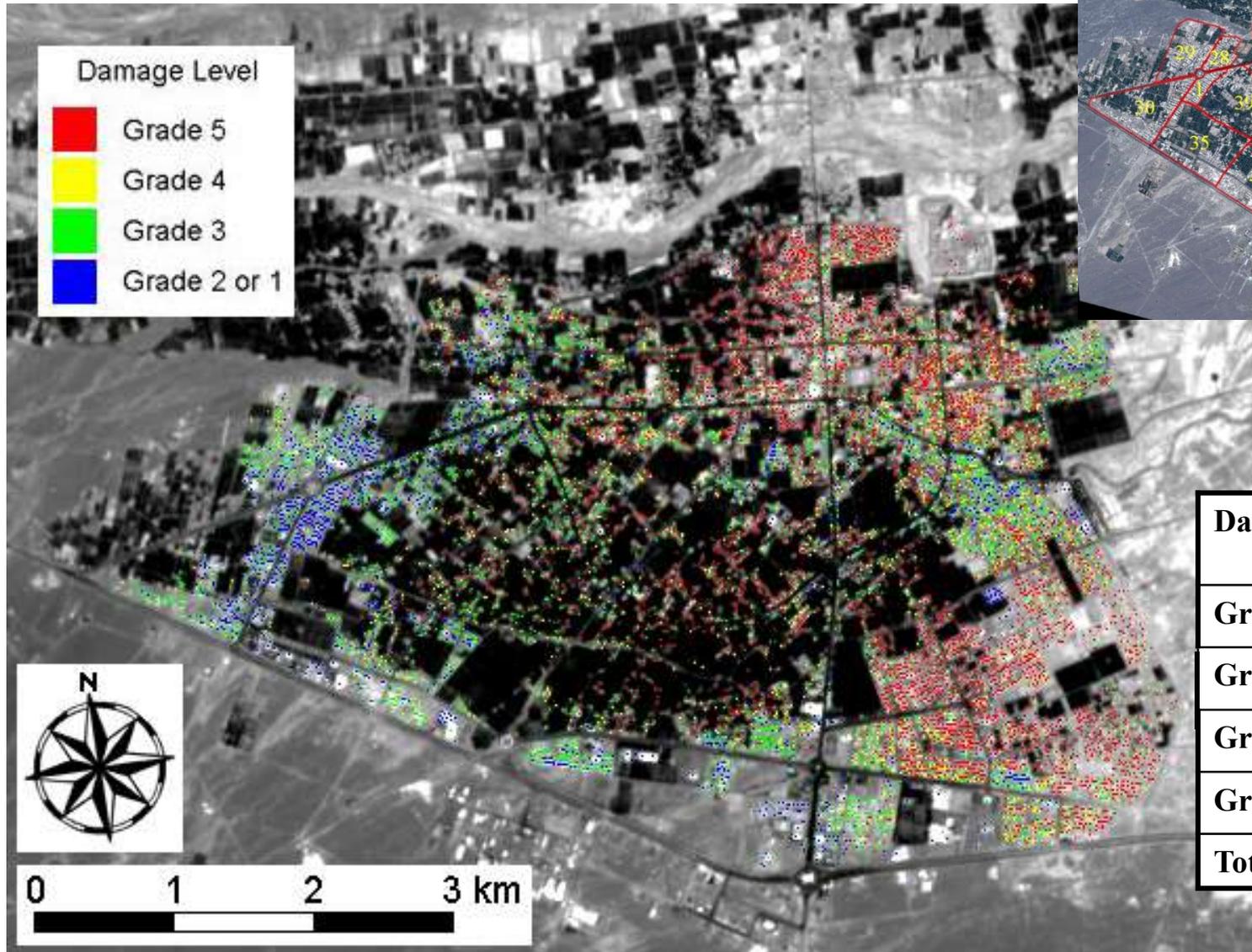


Grade 4



Grade 5

Result of visual damage detection of QB images for Bam City



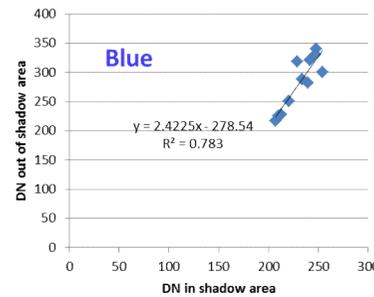
Damage	Number of buildings
Grade 1 & 2	1,597
Grade 3	3,815
Grade 4	1,700
Grade 5	4,951
Total	12,063

Shadow Correction of Optical Image

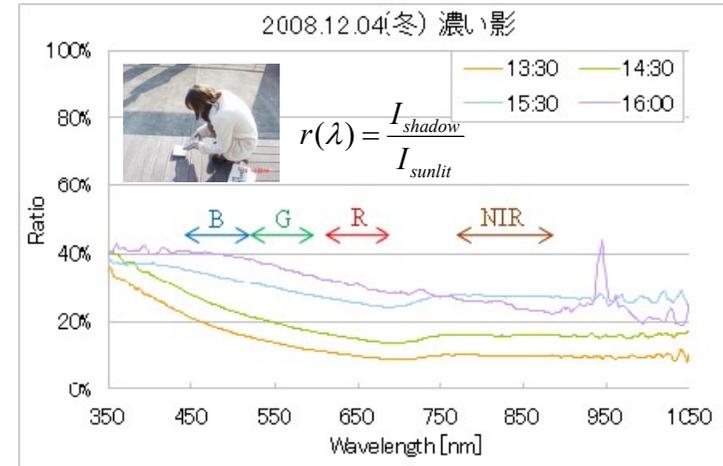
光学画像における影補正



QuickBird Image of Bangkok
November 7, 2002
10:53 AM



Spectroradiometer measurement



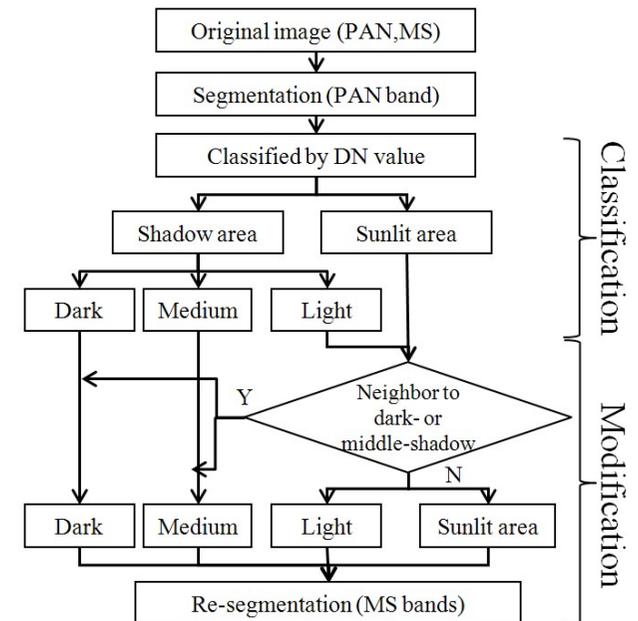
Shadow and non-shadow pairs



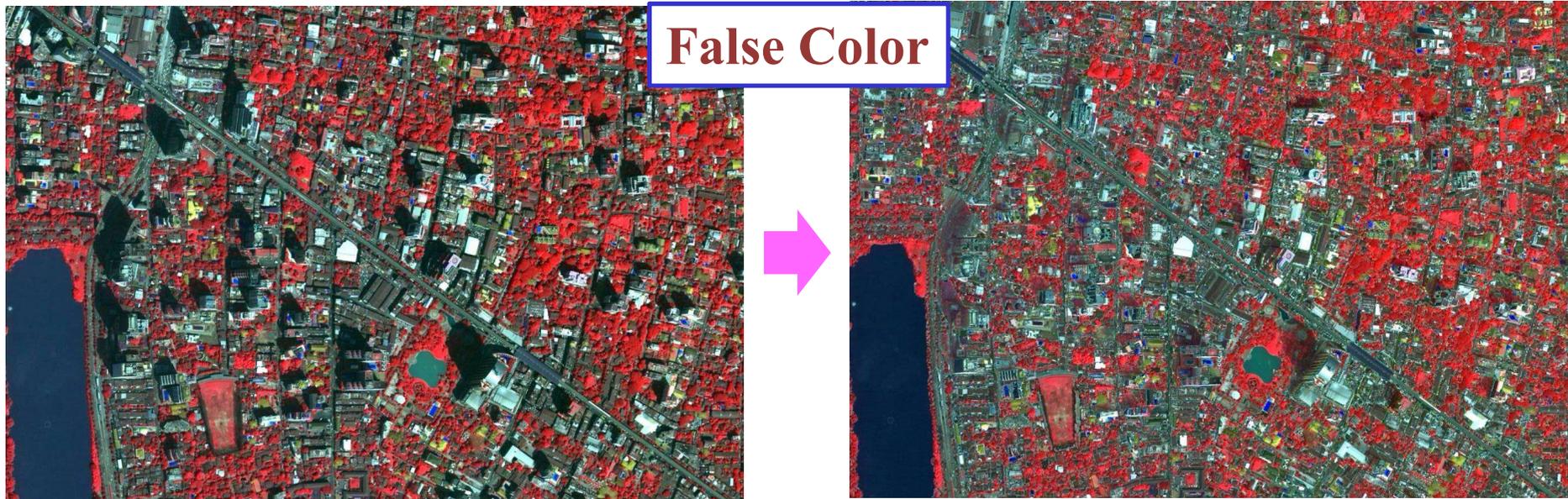
Original image



Corrected image

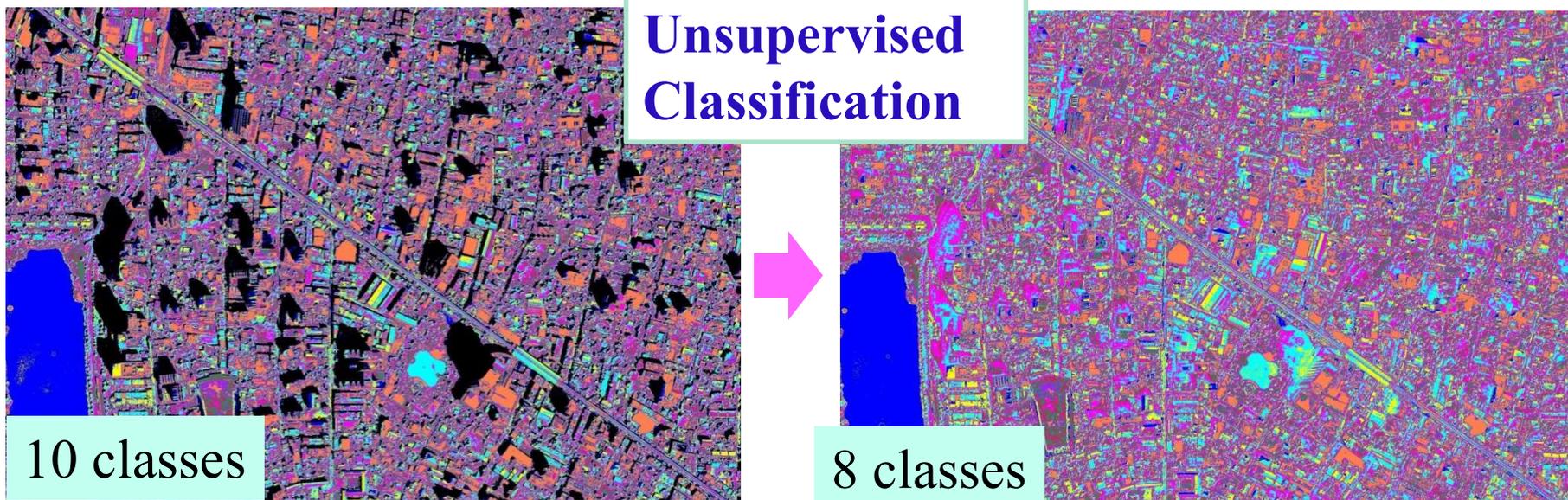


Original and corrected shadow-free QB images



Original image

Corrected shadow-free image



10 classes

8 classes

Satellites that observed the M9.0 2011 Tohoku earthquake

Optical, Medium Resolution

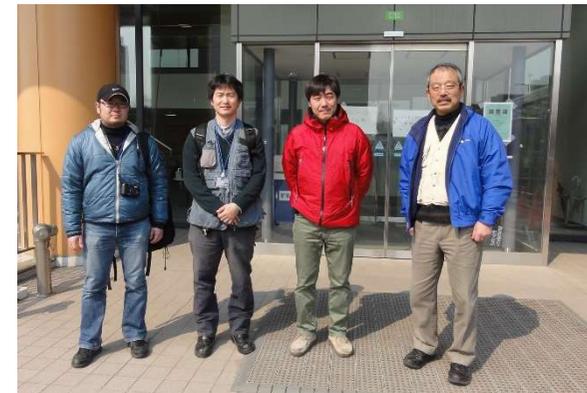
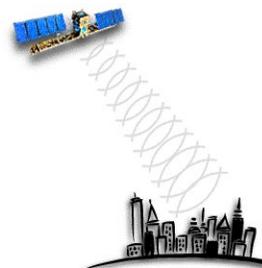
- ALOS AVNIR-2 (10m)
- Terra ASTER (15m)
- Landsat 7 (30m)

SAR

- ALOS PALSAR (L-band, 6.25m)
- Radarsat 1, 2 (C-band, 8m)
- TerraSAR-X (X-band, 3m)
- COSMO-SkyMed (X-band, 3m)

Optical, High Resolution

- FORMOSAT-2 (2.0m)
- THEOS (2.0m)
- RapidEye (2.5m)
- WorldView-1,2 (0.5m)
- QuickBird (0.6m)
- Ikonos (1.0m)
- GeoEye-1 (0.5m)



2011.3.30 @ Sendai

WorldView2 & QuickBird

by Digital Globe

*Aerial survey has been
banned over Fukushima
Daiichi NPP*



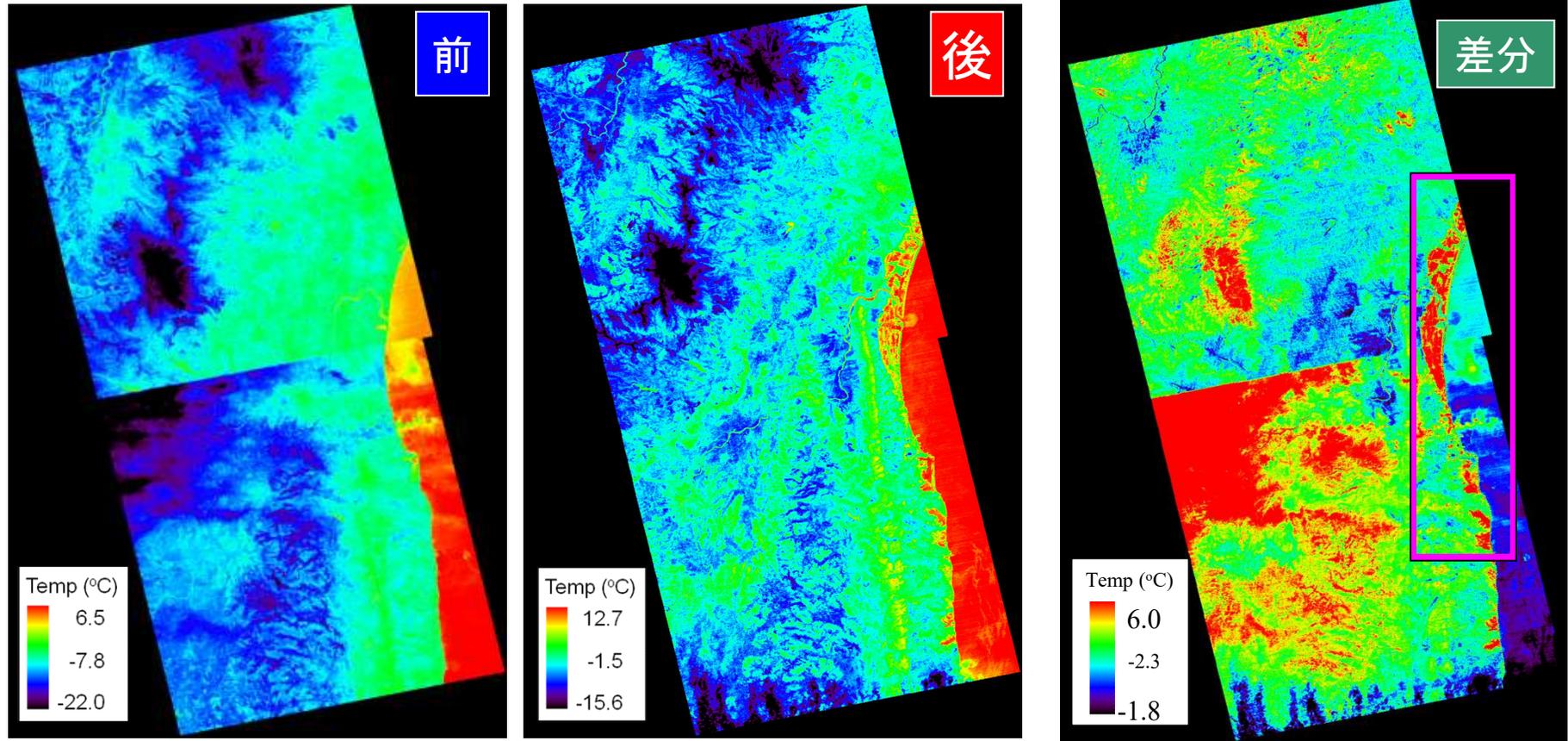
*March 14, 2011 11:04 am,
three minutes after #3 reactor
caused hydrogen explosion*



<http://www.digitalglobe.com/index.php/27/S>

ASTER TIR Images of Soma in the 2011 Tohoku EQ tsunami

東日本大震災前後のASTER夜間熱赤外画像 福島県相馬市



Pre-event:

2010/2/21 & 2008/1/15

Soma City (21:30, **Nighttime**)

Post-event:

2011/3/12

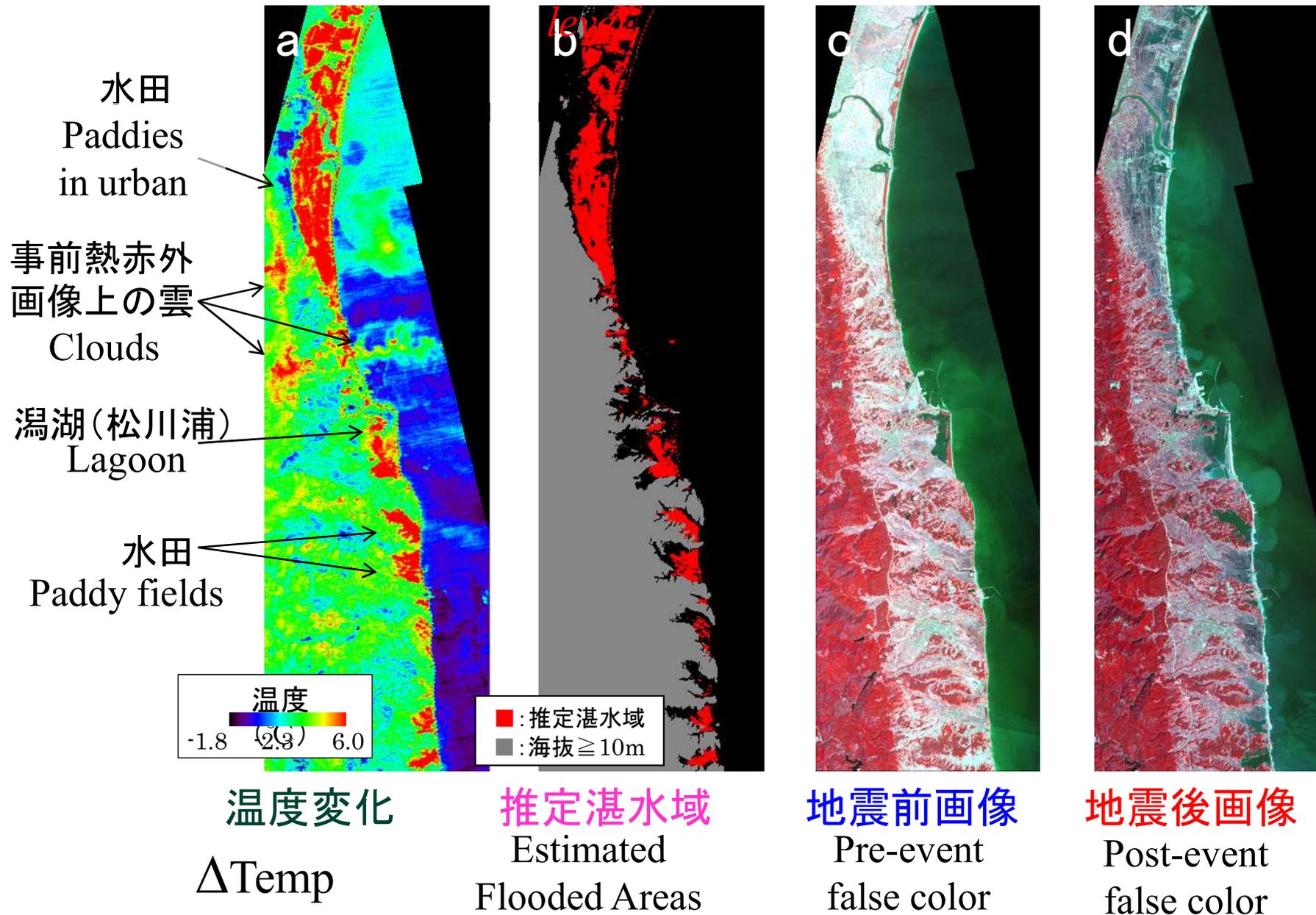
Δ Temp

解像度90m

Tsunami flooded area estimation by ASTER TIR images

Areas more than 5° C increase excluding 9 m above sea

相馬・夜間



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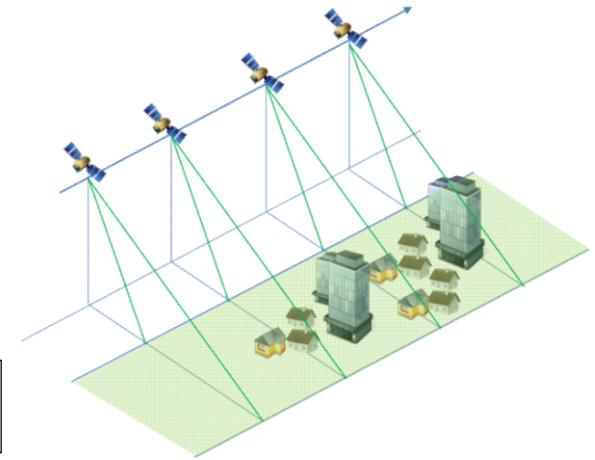
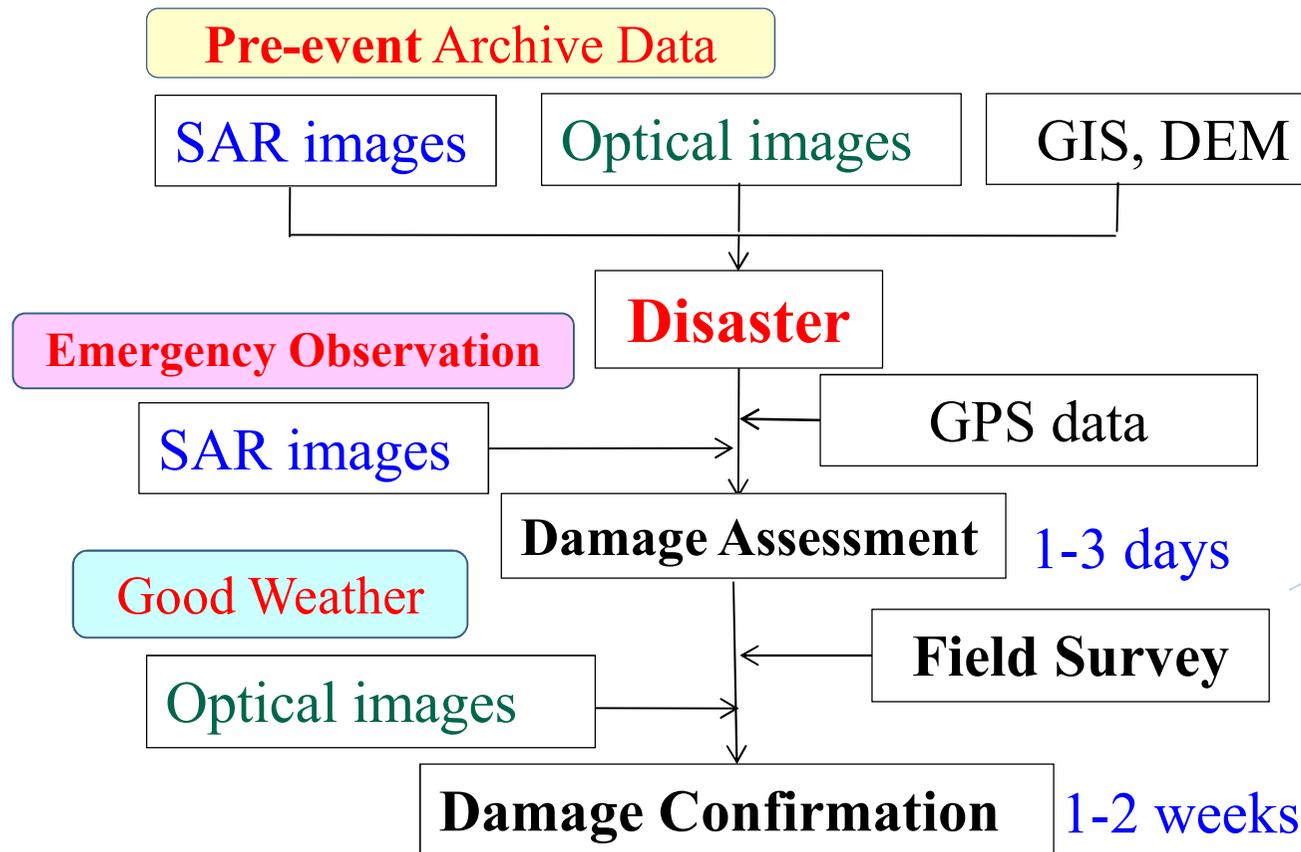
- Satellite Optical and Thermal Sensors

- Satellite SAR

- Airborne SAR

- Lidar and UAV

Flow of post-event damage assessment



Characteristics of SAR

- All Weather, Daytime and Nighttime
- Combined use with GIS and Optical images
- Include height and lateral information due to side-looking mode

Change Detection from SAR intensity images

1. Image matching
2. Speckle noise filtering (*Lee Filter*)
3. Calculating following indices:

✓ **Difference of backscattering coefficients** (after – before)

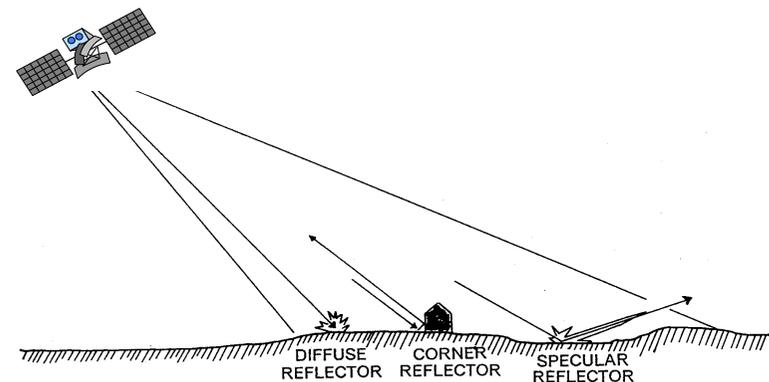
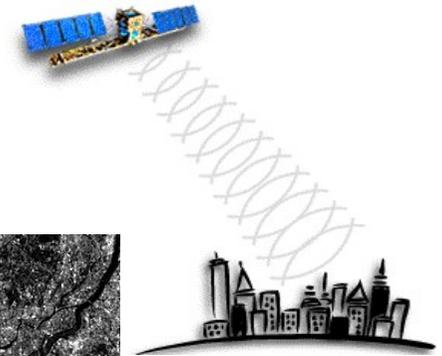
$$d[dB] = \bar{I}a_i - \bar{I}b_i$$

✓ **Correlation coefficient**

$$r = \frac{N \sum_{i=1}^N I a_i I b_i - \sum_{i=1}^N I a_i \sum_{i=1}^N I b_i}{\sqrt{\left(N \sum_{i=1}^N I a_i^2 - \left(\sum_{i=1}^N I a_i \right)^2 \right) \cdot \left(N \sum_{i=1}^N I b_i^2 - \left(\sum_{i=1}^N I b_i \right)^2 \right)}}$$

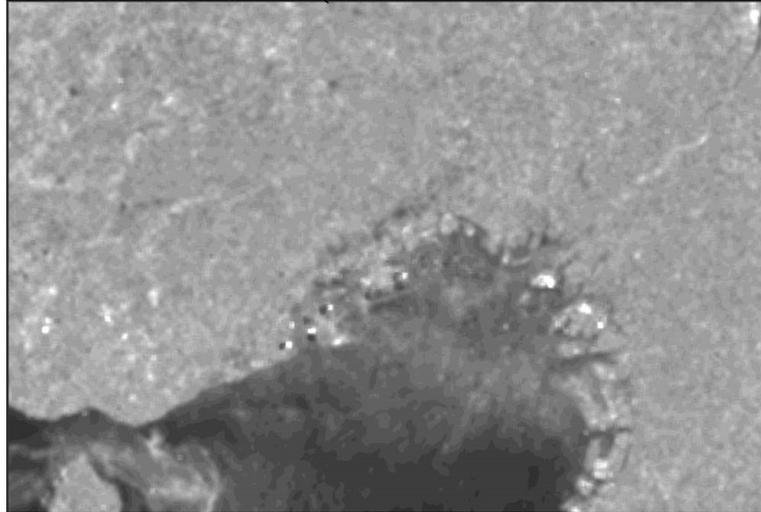
$I a_i$ and $I b_i$ are the digital numbers of the post- and pre-images.

$\bar{I} a_i$ and $\bar{I} b_i$ are the corresponding averaged digital numbers **over the pixel window**. 23

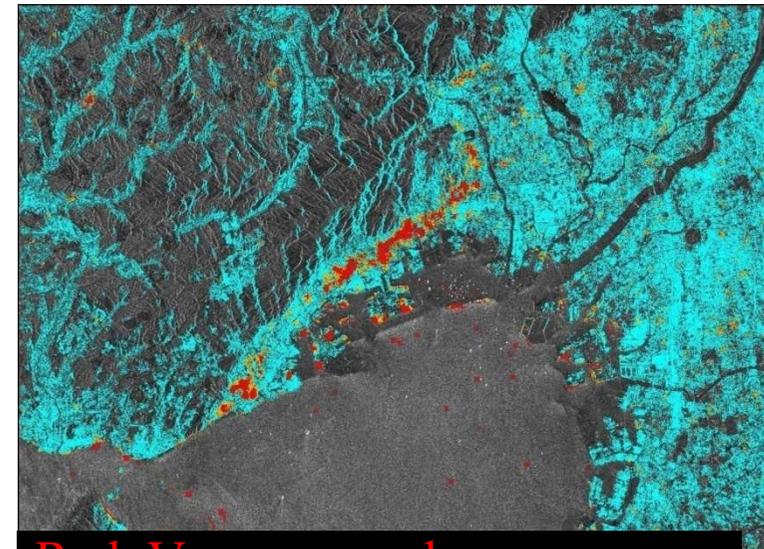
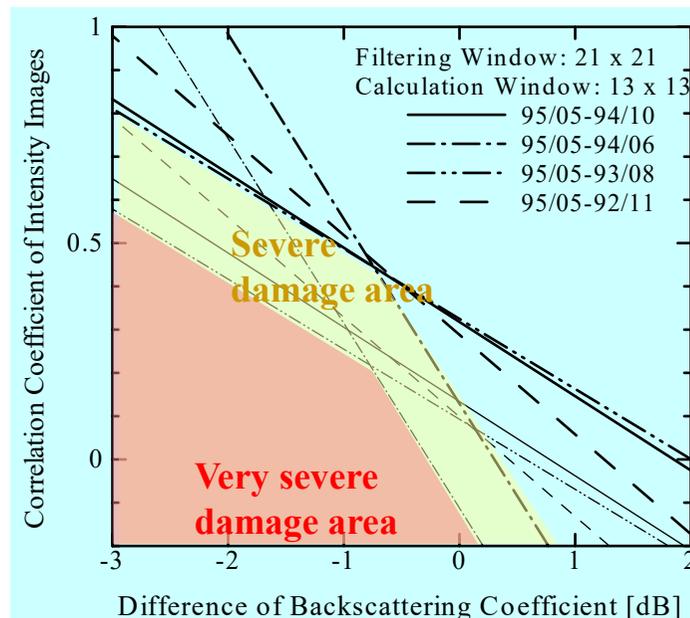
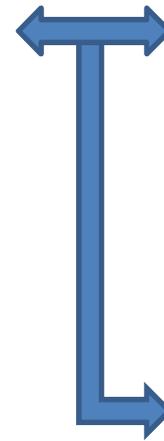
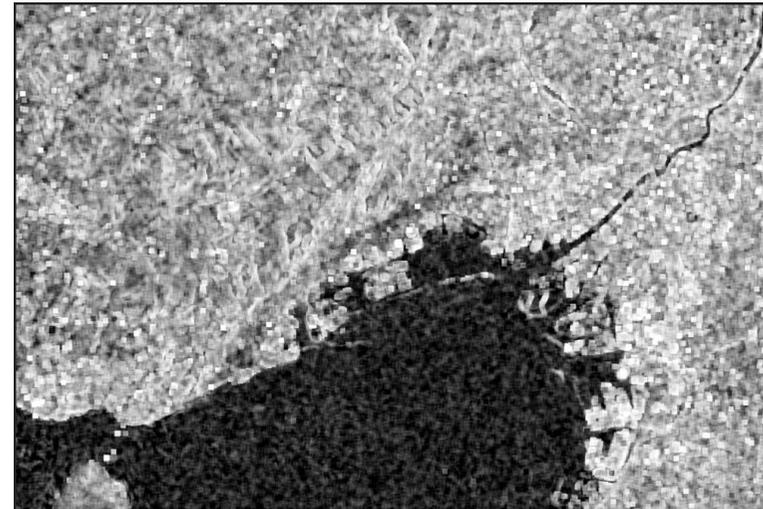


Estimated Damage Areas in 1995 Kobe EQ using ERS/SAR

✓ **Difference of backscattering coefficient** (1995/5/23 – 1994/6/3)



✓ **Correlation coefficient**



Red: Very severe damage area
Yellow: Severe damage area

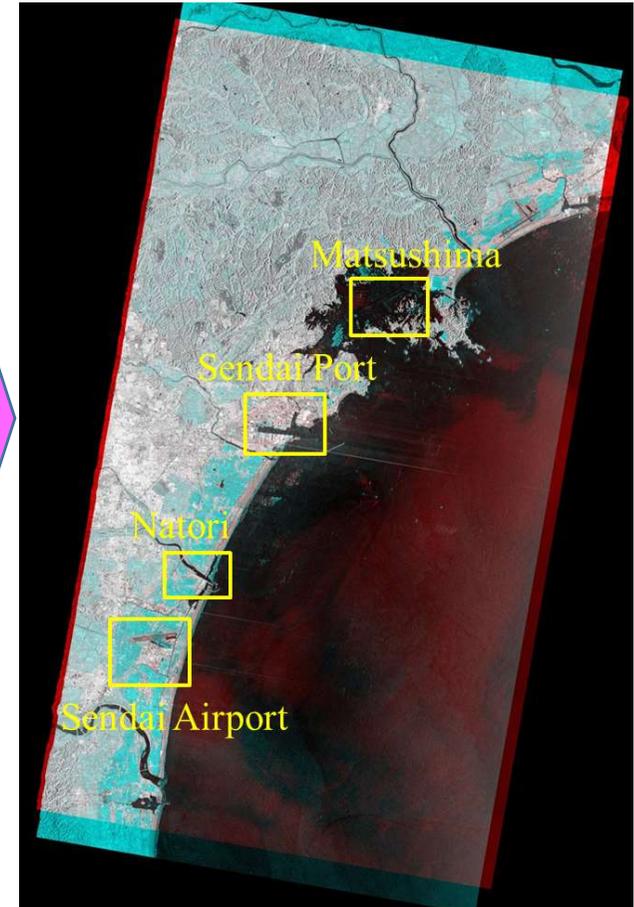
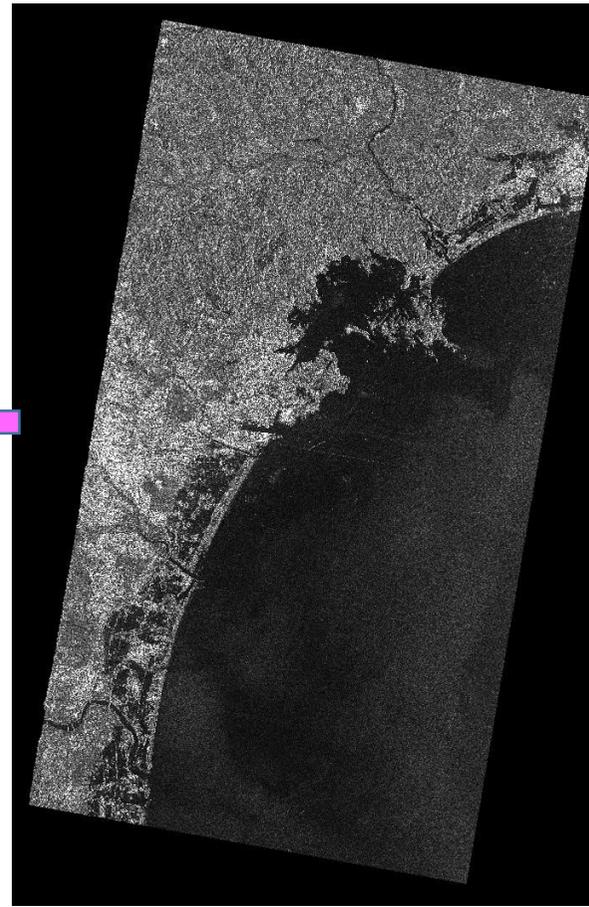
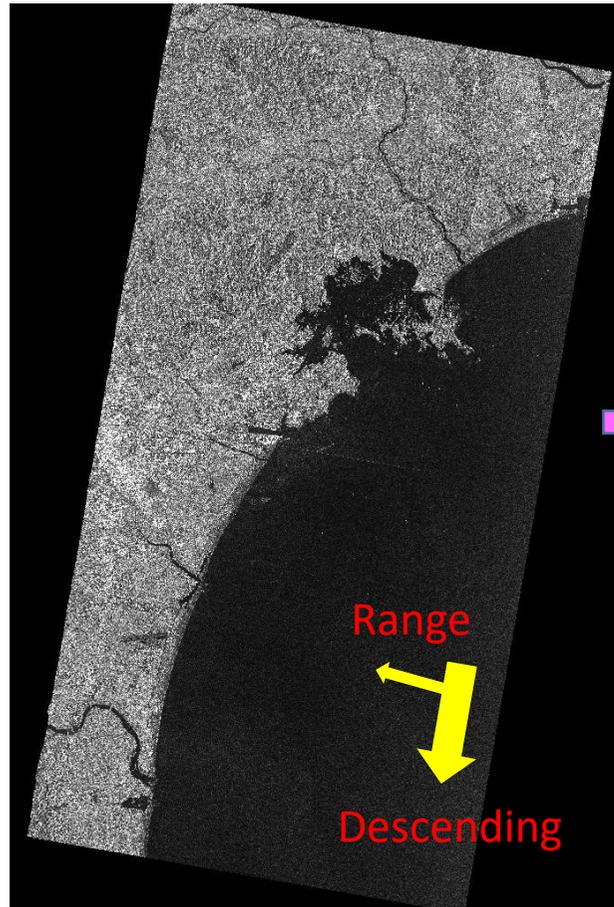
TerraSAR-X intensity data of Sendai area for the 2011 Tohoku EQ

Pre-event

Post-event

R: 2011/03/13

G&B: 2010/10/21



UTC: 2010/10/20, 20:43
Japan ST: **2010/10/21**, 5:43
Incidence angle: 37.32°

UTC: 2011/03/12, 20:43
Japan ST: **2011/03/13**, 5:43
Incidence angle: 37.30°

■ Reduced backscatter
Flooded areas etc.
■ Increased backscatter
Debris etc.

StripMap mode, HH polarization

Movement of an intact building in SAR images

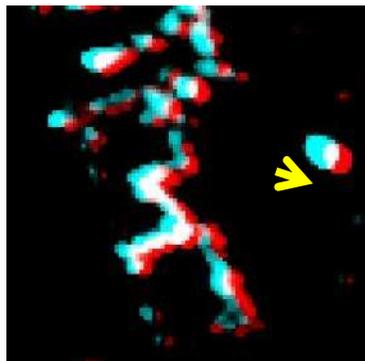
Pre-event



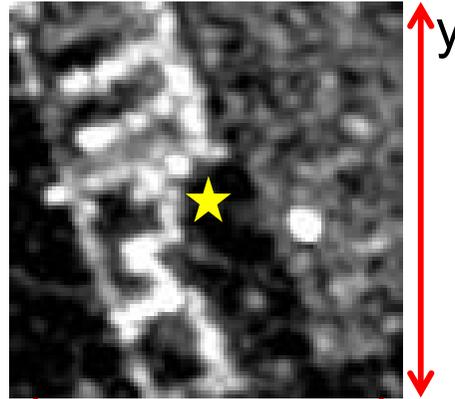
Post-event



Color composite

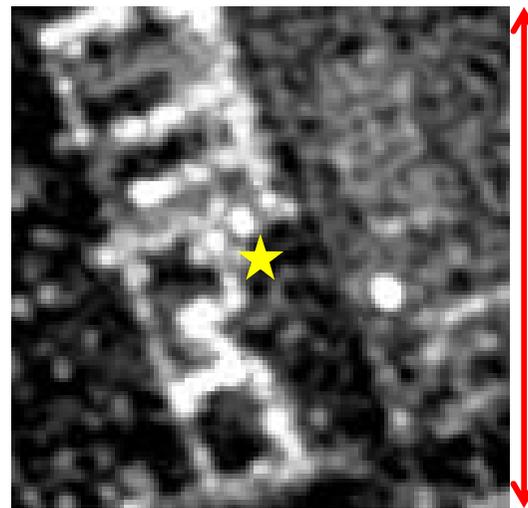


T: Pre-event SAR



101 x 101 pixels **X**

I: Post-event SAR



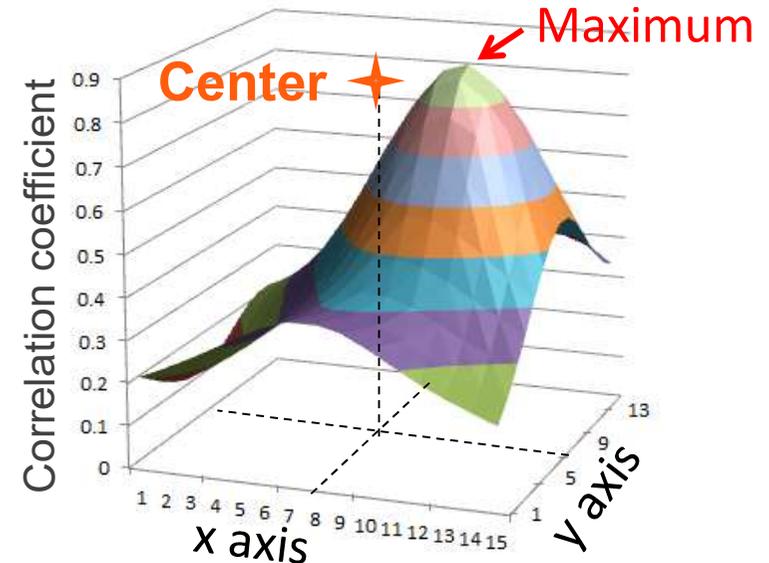
115 x 115 pixels

Area-based correlation

$$R(a,b) = \frac{\sum_{i=0}^{M_T-1} \sum_{j=0}^{N_T-1} \{I_{(a,b)}(i,j) - \bar{I}\} \{T(i,j) - \bar{T}\}}{\sqrt{\sum_{i=0}^{M_T-1} \sum_{j=0}^{N_T-1} \{I_{(a,b)}(i,j) - \bar{I}\}^2} \sqrt{\sum_{i=0}^{M_T-1} \sum_{j=0}^{N_T-1} \{T(i,j) - \bar{T}\}^2}}$$

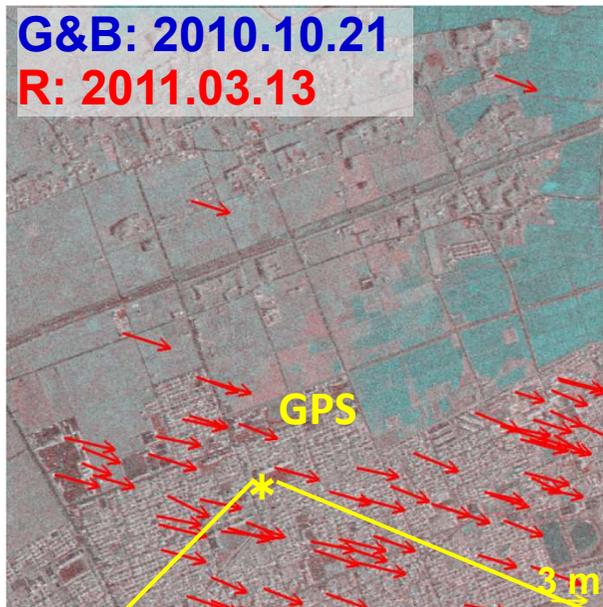
$$\bar{I} = \frac{1}{M_T N_T} \sum_{i=0}^{M_T-1} \sum_{j=0}^{N_T-1} I_{(a,b)}(i,j) \quad \bar{T} = \frac{1}{M_T N_T} \sum_{i=0}^{M_T-1} \sum_{j=0}^{N_T-1} T(i,j)$$

Correlation Matrix



3.75 m to east, 1.25 m to south
(1.25m/pixel)

Estimation of crustal movements at GPS Yamoto

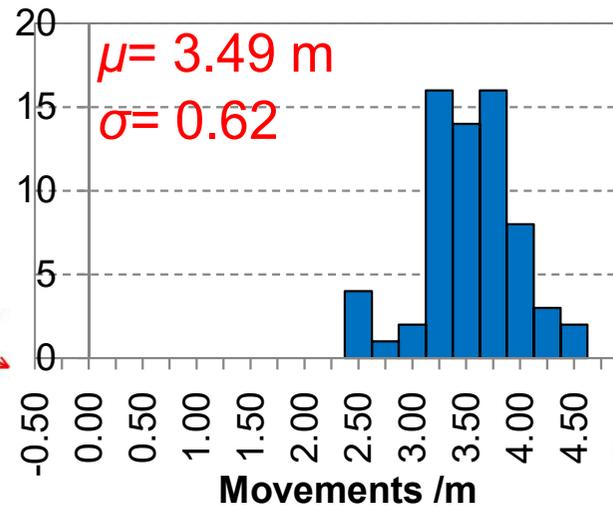


67 buildings

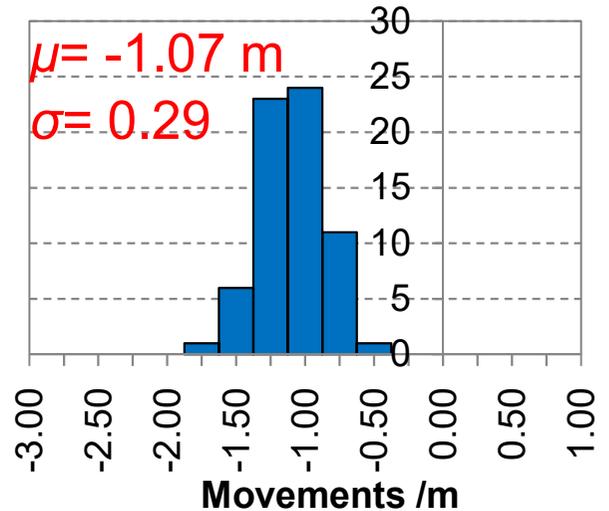


Google Earth 2011.04.06

East

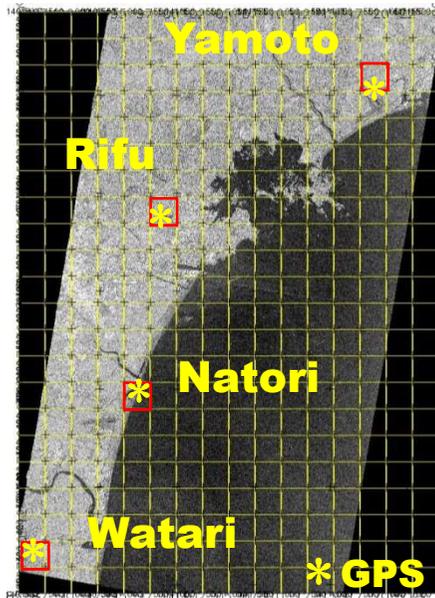


North

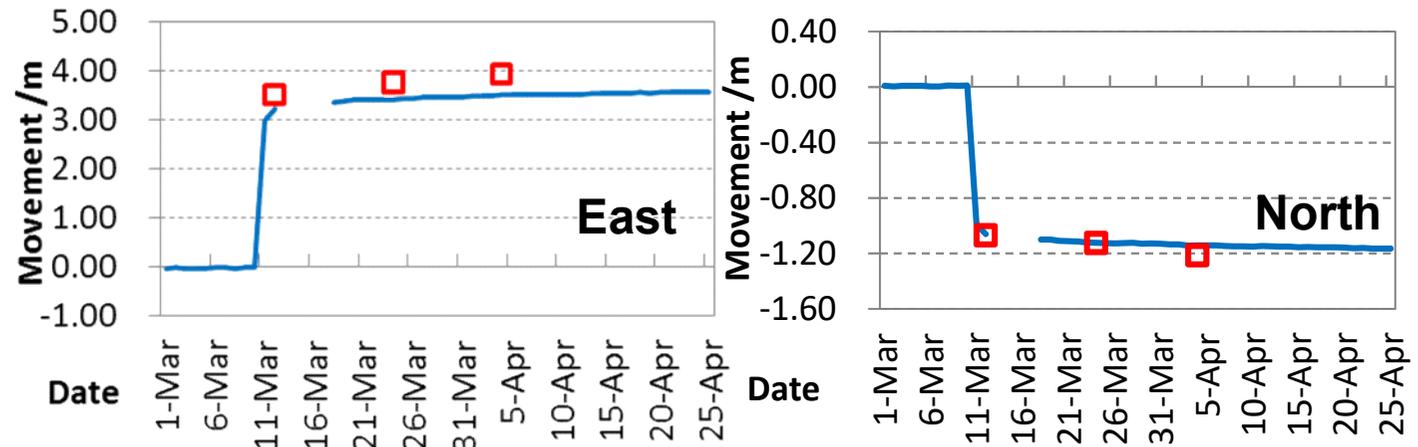


Survey photo 2012.01.14

Comparison with GPS observed data



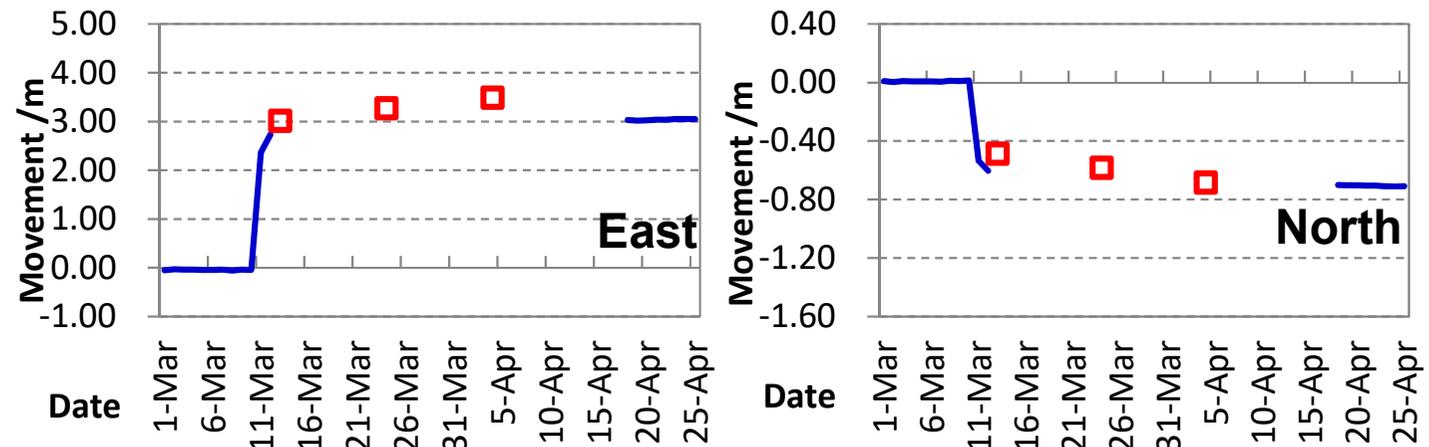
— GPS observed data □ Detected results



Yamoto



— GPS observed data □ Detected results



Natori

Fukushima Daiichi nuclear power plant in September 2011

福島第一原子力発電所の事故後の状況



#1 reactor building



#2 reactor building

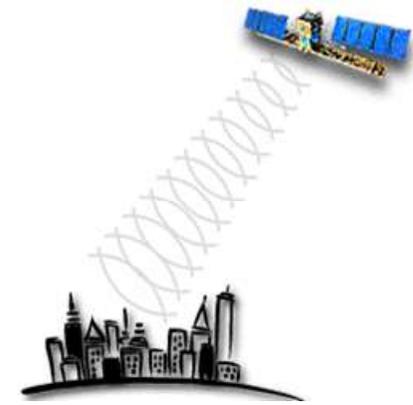


#3 reactor building

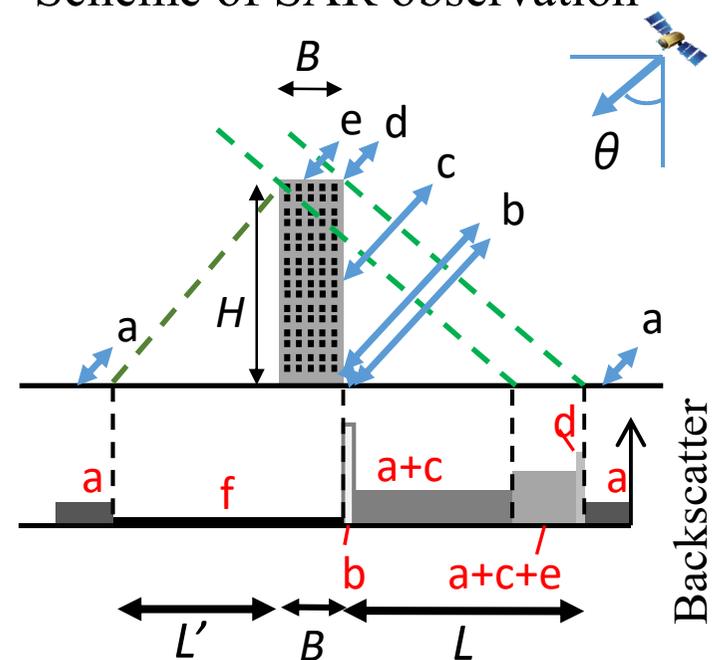


#4 reactor building

Photos by TEPCO on 2011/09/15



Scheme of SAR observation



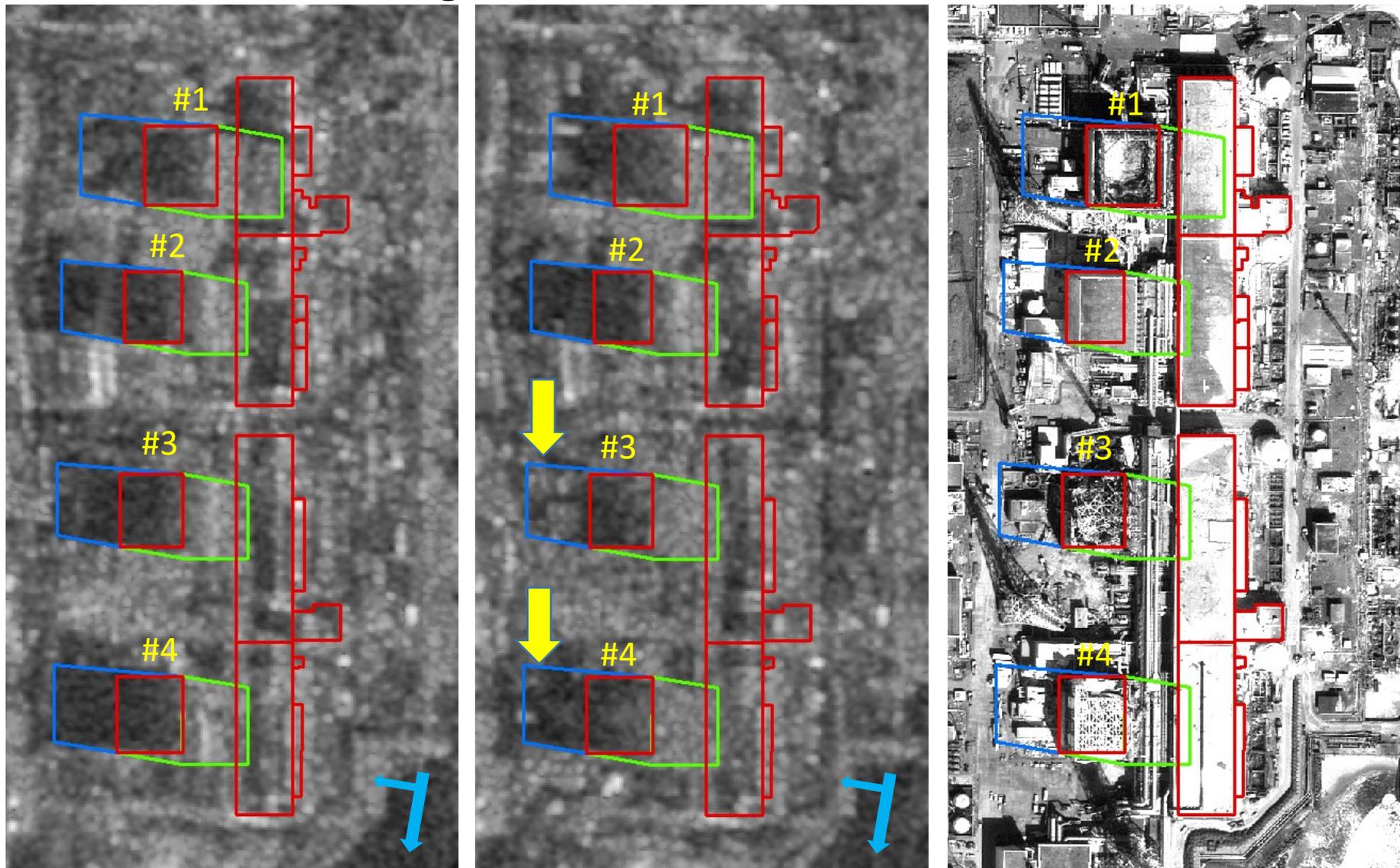
Radar Shadow

Layover

$$L' = H \tan \theta$$

$$L = H / \tan \theta$$

TerraSAR-X images of Fukushima Daiichi NPP after EQ



TSX 2011/03/13 05:43

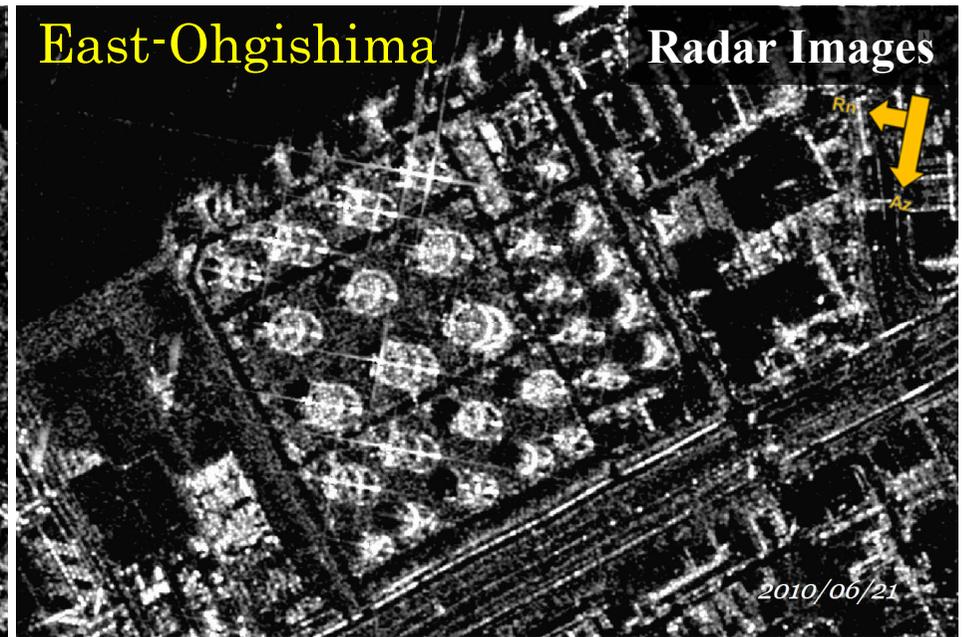
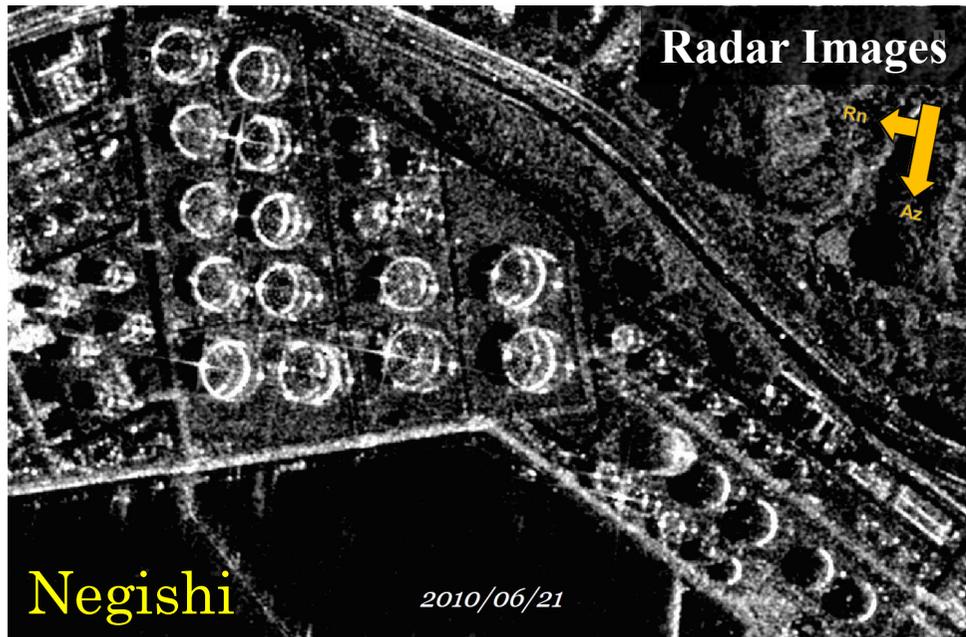
TSX 2011/09/05 05:43

GeoEye-1 2011/09/16 09:33

— Layover

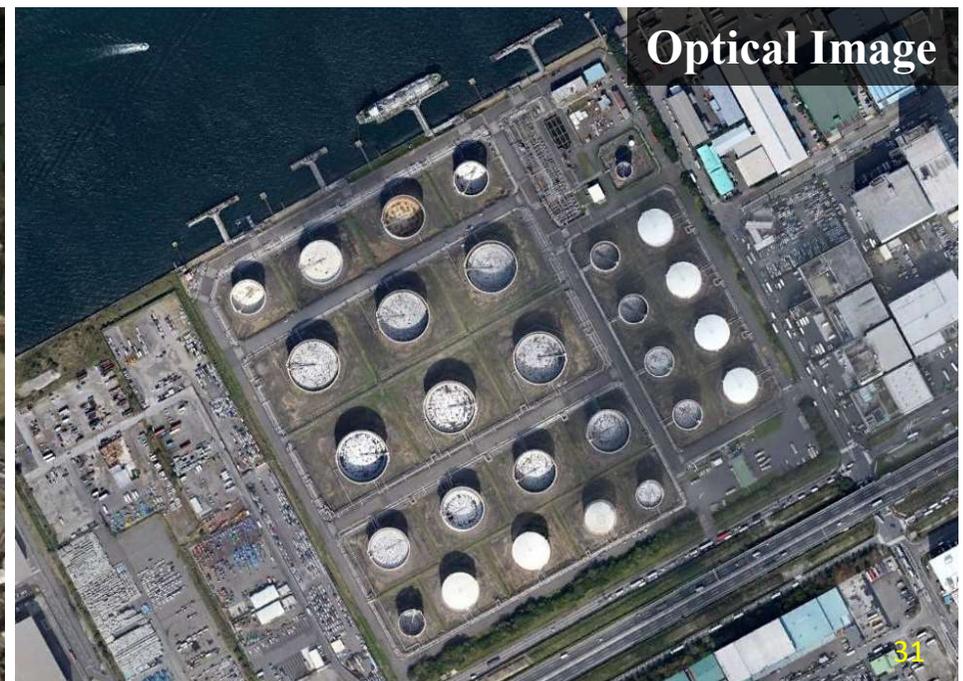
— Radar Shadow

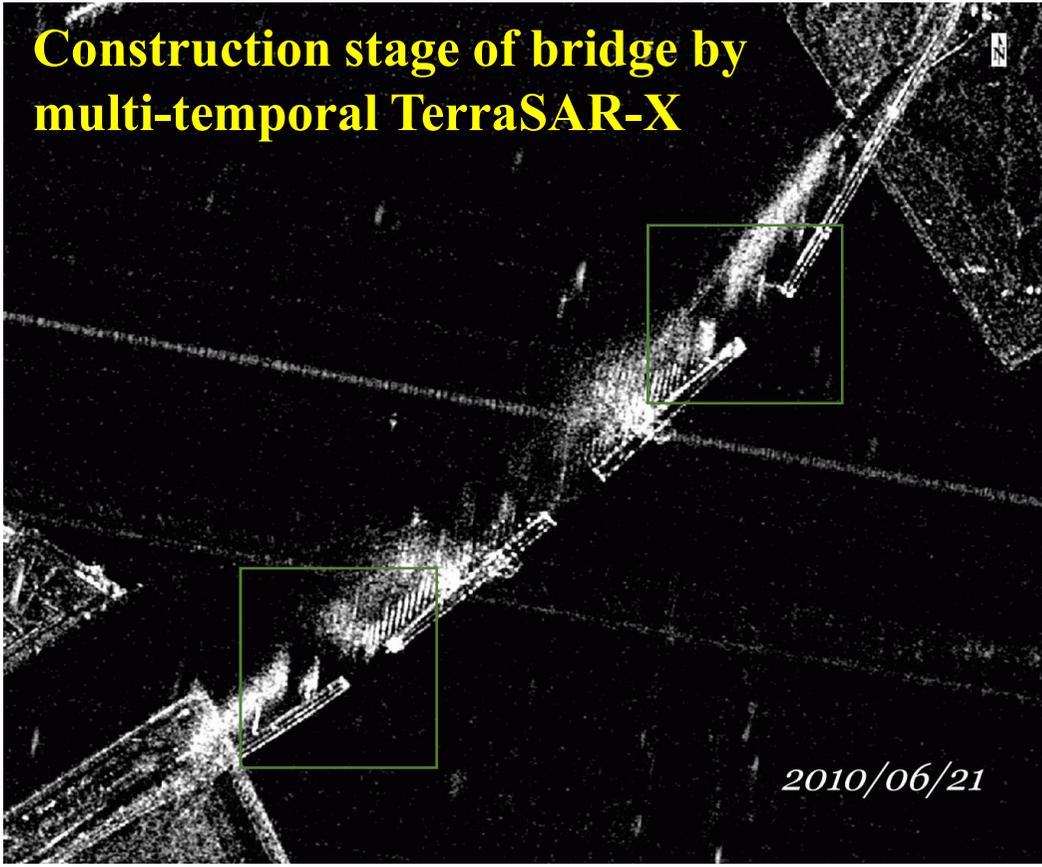
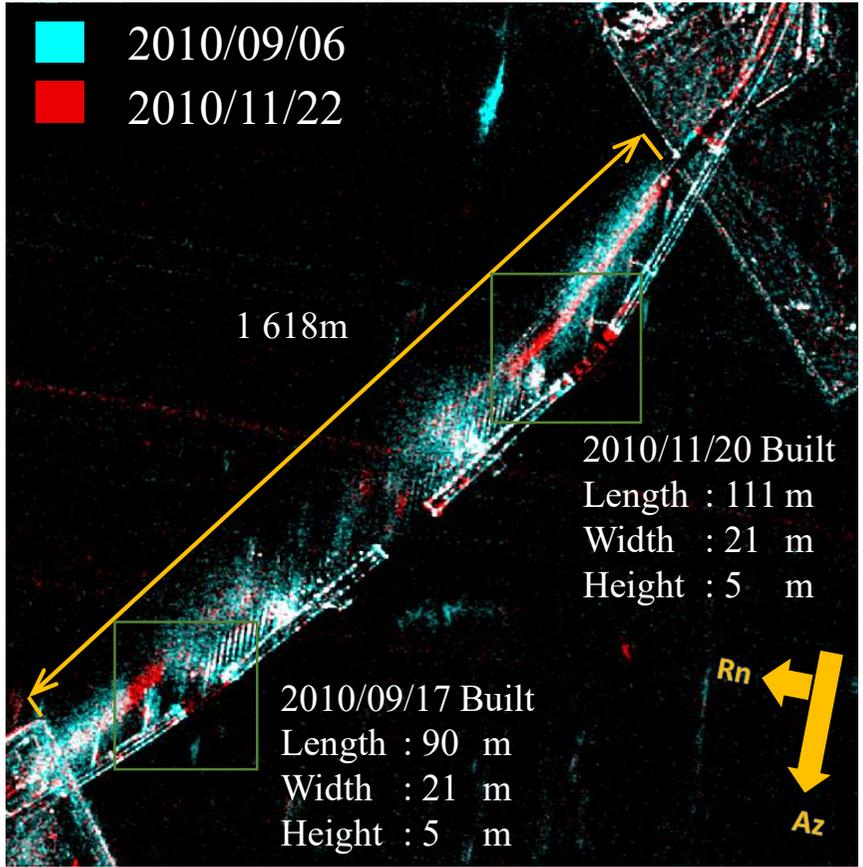
— Building Footprint



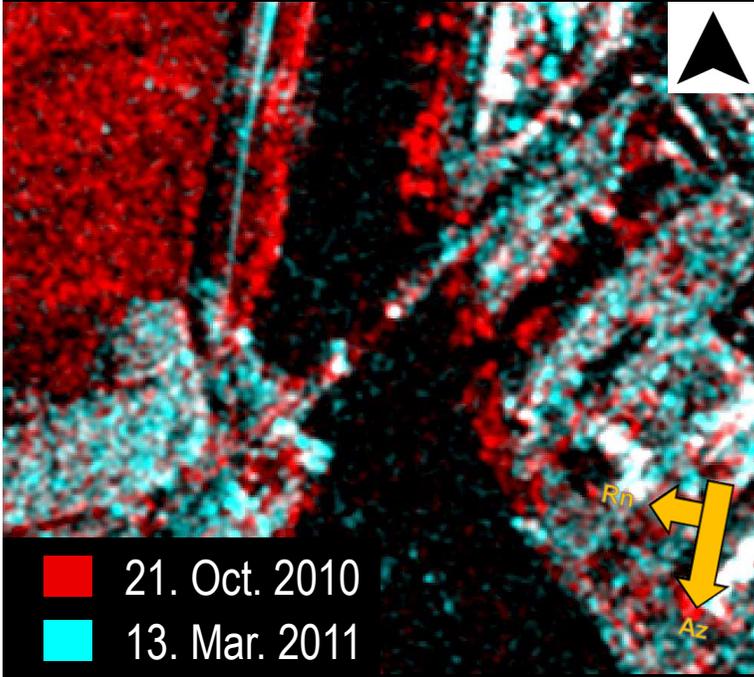
Acquisition : 2010/06/21,
2010/09/06,
2010/11/22

TerraSAR-X images of **floating-roof-type oil tanks** in Japan

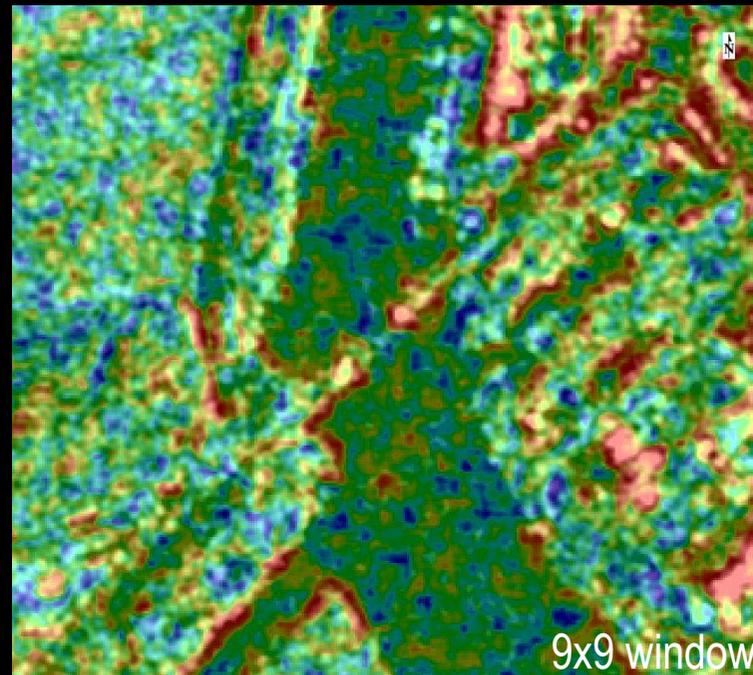
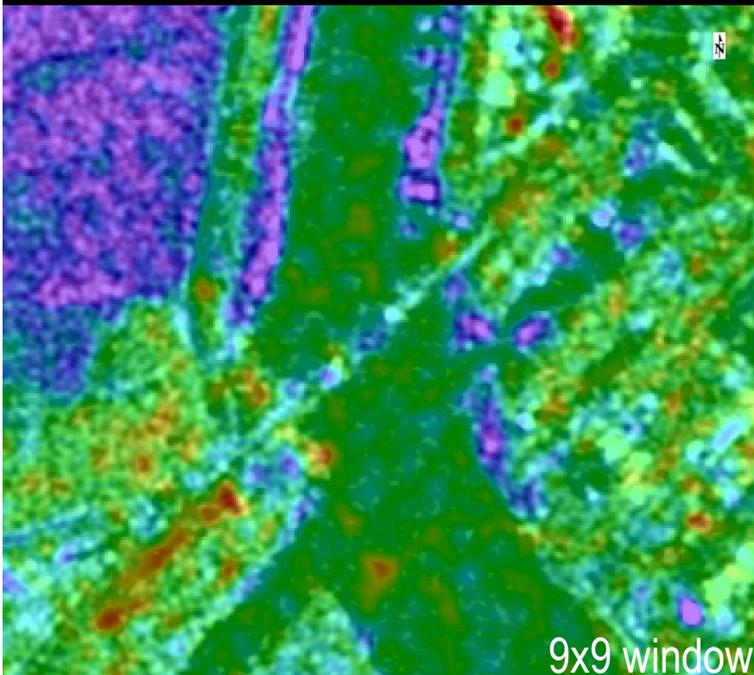




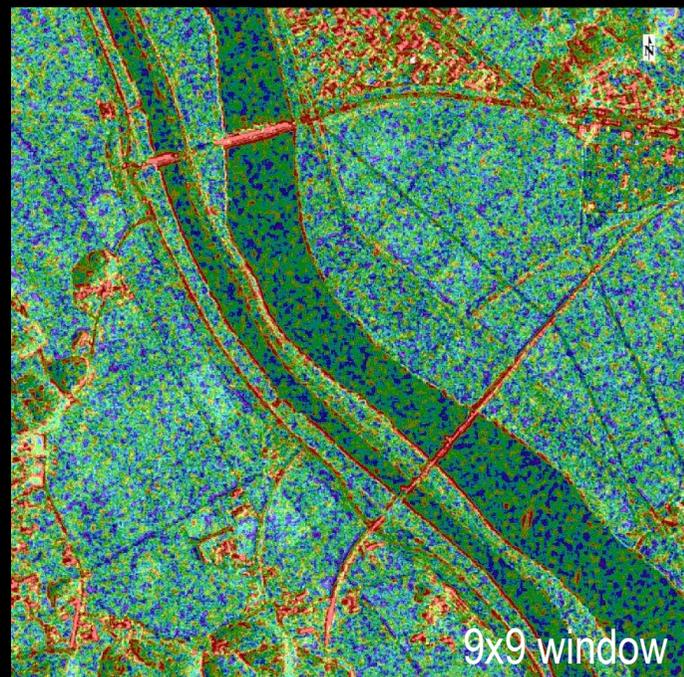
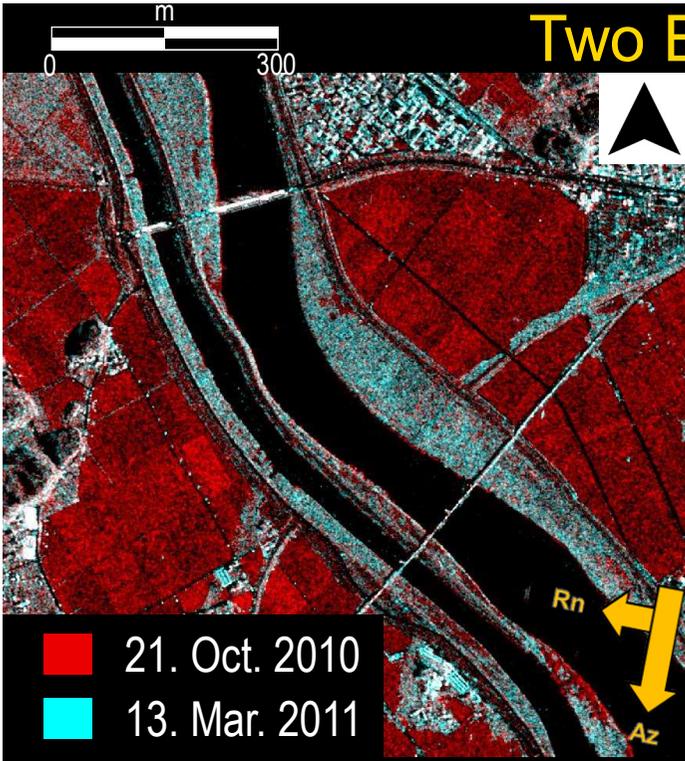
a. Jogawa Bridge (L=126.0m)



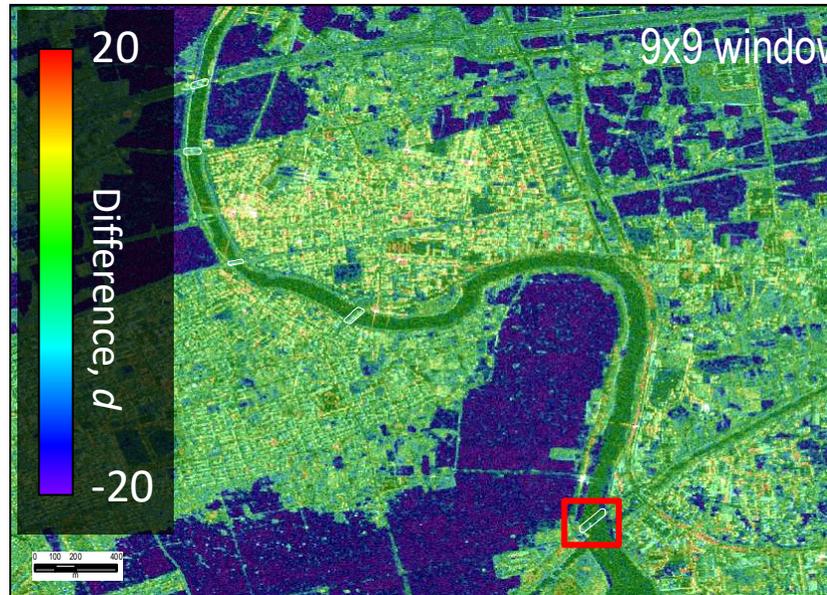
Orbit Dir. : Desc.
Look Dir. : Right
Imaging Mode : StripMap
Pixel Res. : 1.25m/pix
Polarization : HH
Product Level : EEC



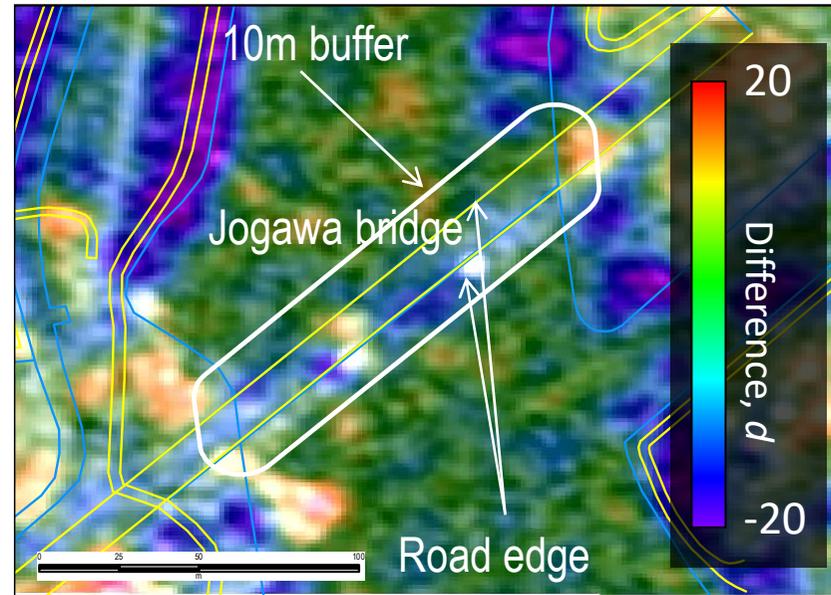
Two Bridges over Naruse River



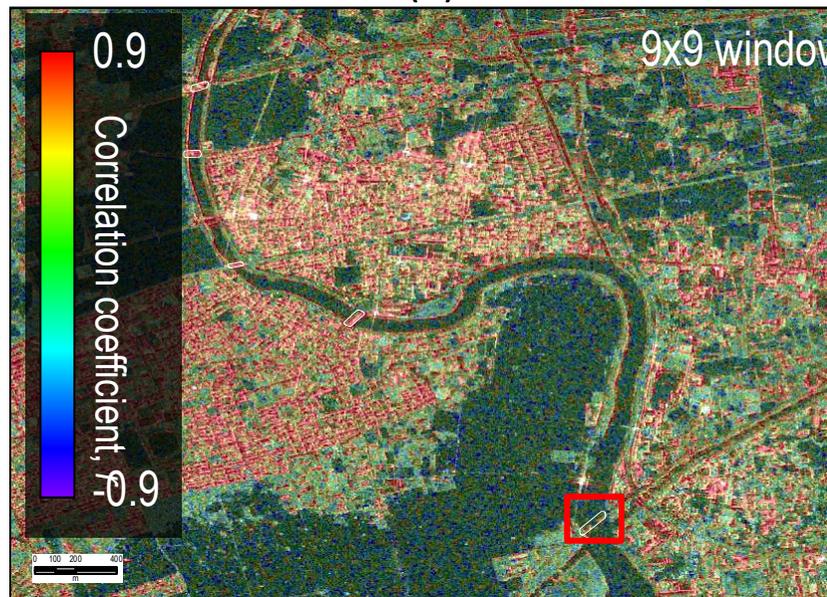
Change Detection for Enlarged Bridge Footprint



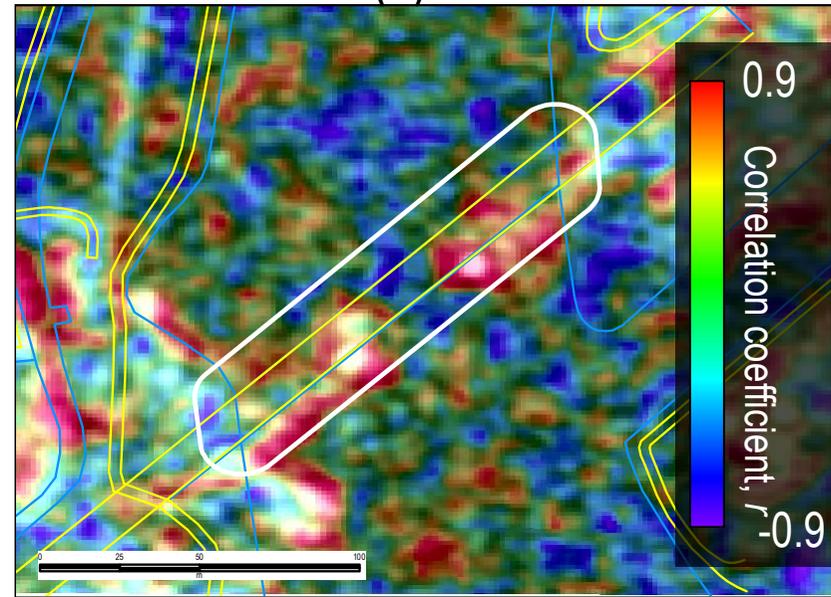
(a)



(b)

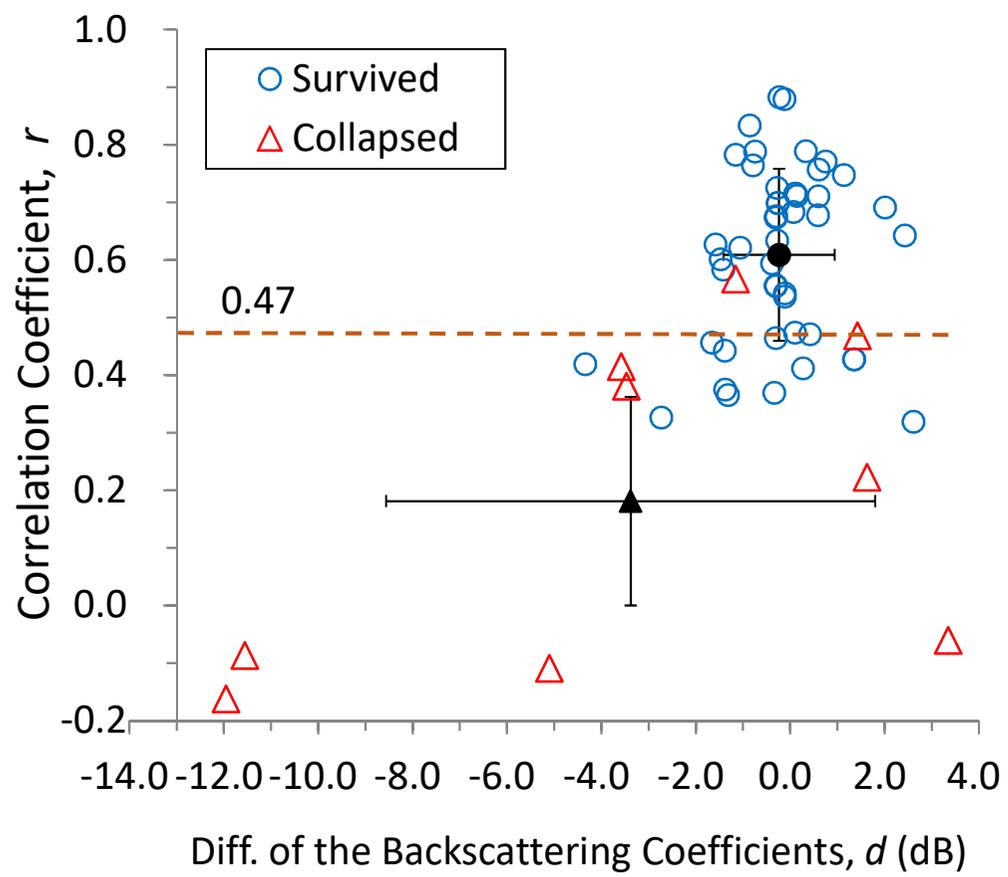


(c)

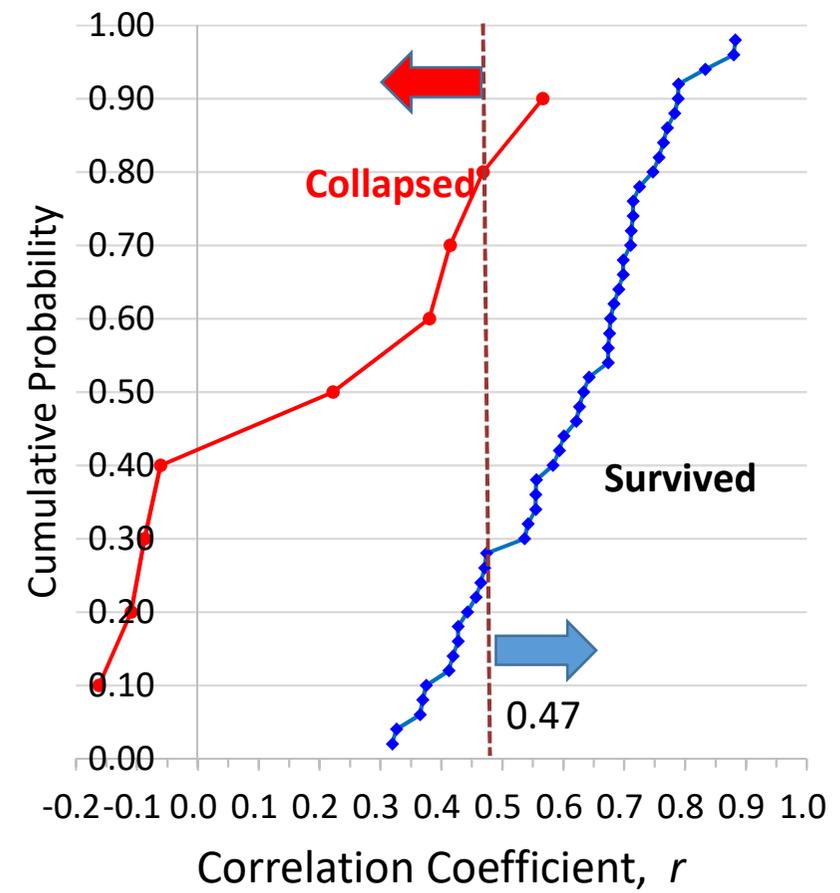


(d)

Relationship between the difference d and correlation coefficient r (a) and the cumulative probability of r when the threshold was set as $r=0.47$ (b) for the 58 bridges

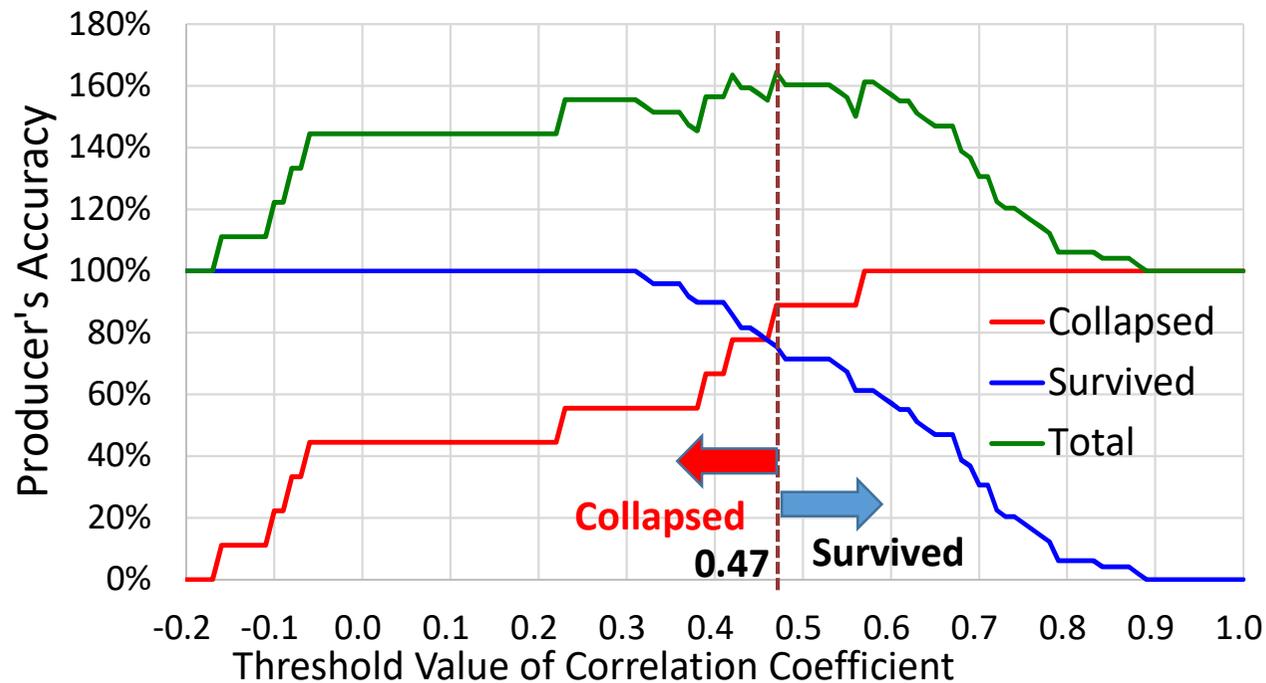


(a)



(b)

Change of the producer accuracies as a function of threshold of r



Error Matrix for the threshold $r = 0.47$

		Reference Data			User's Accuracy
		Collapsed	Survived	Total	
SAR Image Interpretation	Collapsed	8	12	20	0.400
	Survived	1	37	38	0.974
	Total	9	49	58	
Producer's Accuracy	Producer's Accuracy	0.889	0.755		
	Overall Accuracy				0.776
	Kappa Coefficient				0.430

Contents

- Remote Sensing and Disaster Management
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- Lidar and UAV

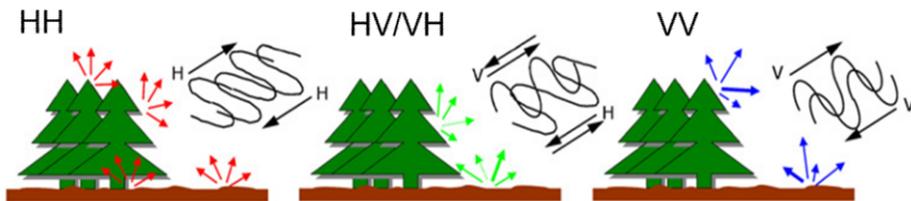
Multi-polarized Pi-SAR-L2 image for the study area

Natori and Iwanuma cities, Miyagi prefecture, Japan.

JAXA



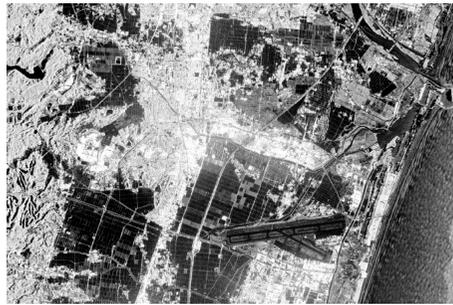
R: HH, G: HV, B: VV



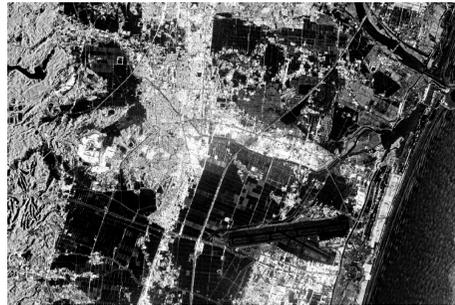
	Pi-SAR-L2	
Date	2014/6/12	
Band	L-band	
Azimuth resolution	1.76 m	
Range resolution	3.2 m	
Pixel size	2.5 m/pixel	
Polarization	HH / HV / VH / VV	

Texture measures for the HH-polarized Pi-SAR-L2 image

Gray-Level Co-occurrence Matrix (GLCM)



(a) mean



(b) variance



(c) homogeneity



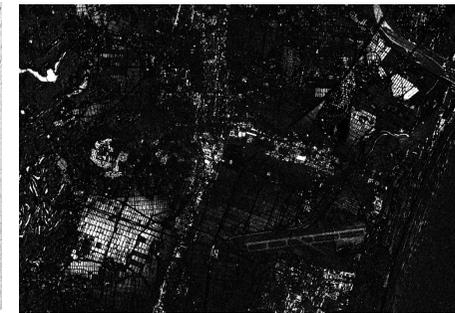
(d) contrast



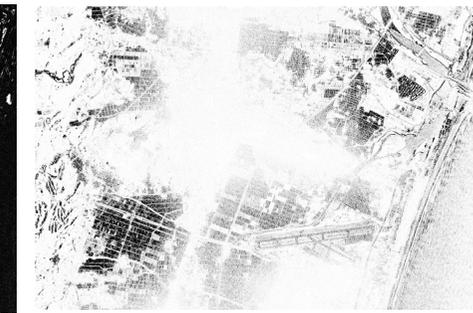
(e) dissimilarity



(f) entropy



(g) angular second moment



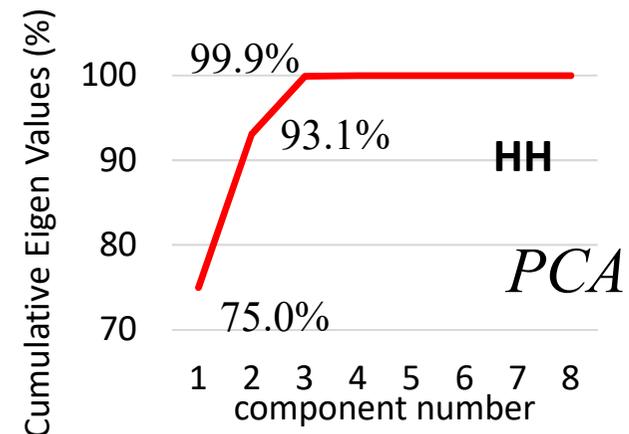
(h) correlation

Eight textural features in angle 0°

Distance 1

Window size of 9 x 9
using ENVI software

Original Image



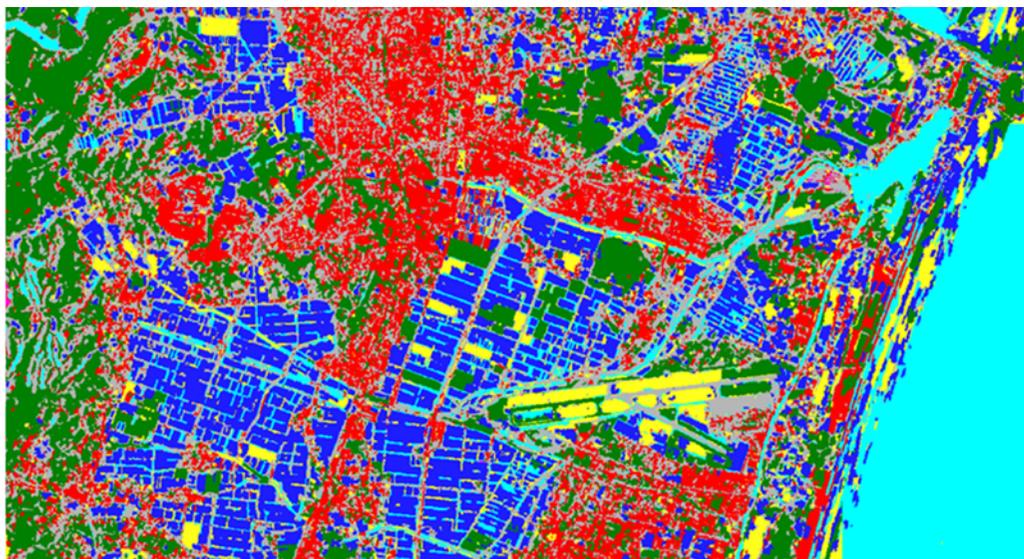
Object-based supervised land-cover classification result



Original HH and HV pols.

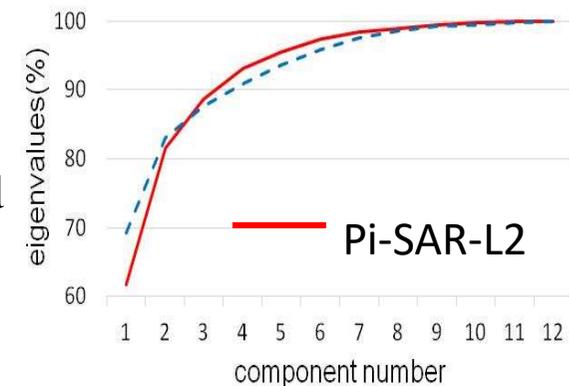


- Water and roads are difficult to classify.
 - False positive errors for solar panels.
 - The results are similar for 5 PCs and 8 PCs textures.
- 95 % cumul. Eigenvalue is enough.

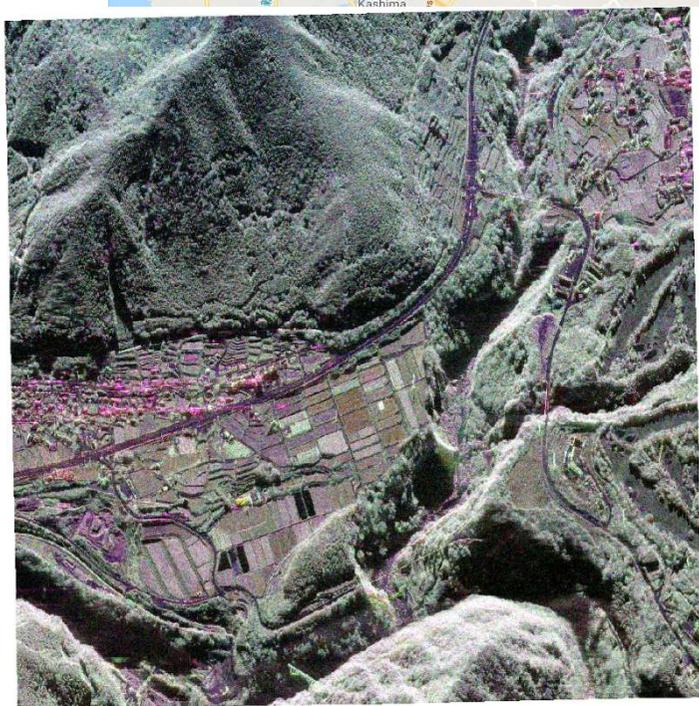
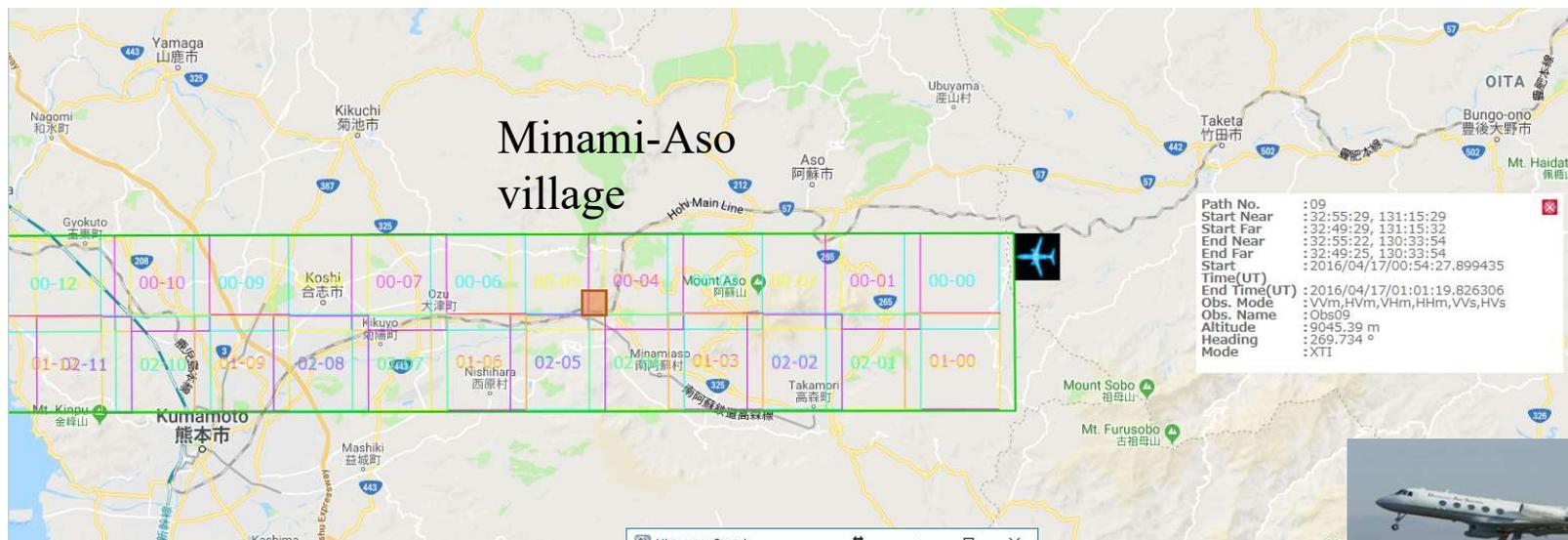


Original HH and HV + 5 PC textures (95.5 %)

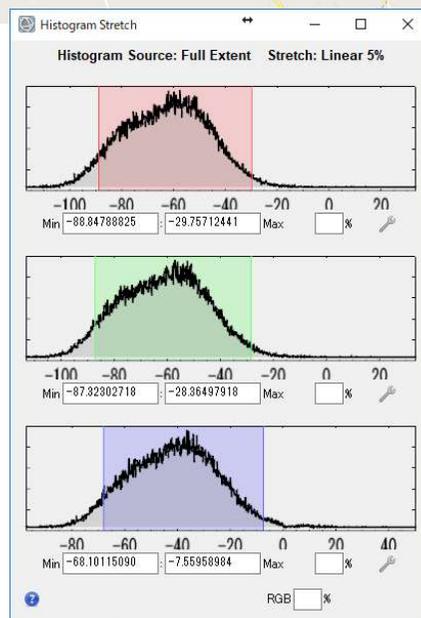
- tree
- grass
- road
- water
- paddy field
- urban
- solar panel



Pi-SAR2 (X2) flight after the 2016 Kumamoto EQ by NICT



R:HH, G:HV, B:VV



Polarimetric and Interferometric Airborne SAR (Pi-SAR-X2)

Date	Height (m)	Heading
2015.12. 5	8981 m	-91.3°
2016. 4.17	9027 m	-90.3°

Resolution (m): 0.3 (A) x 0.3 (R)

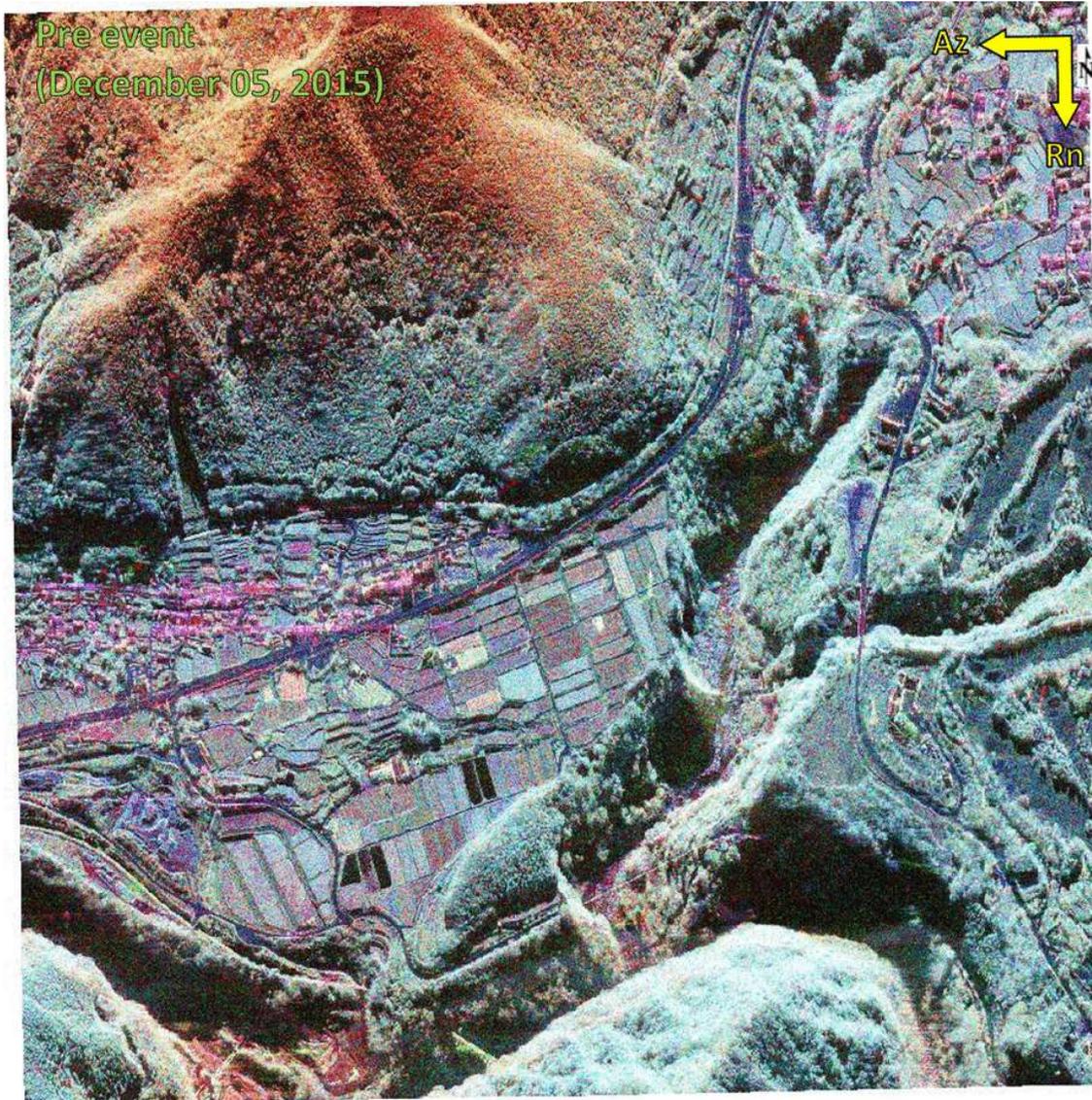
Pixel size (m): 0.25 x 0.25

Enhanced Lee Filter : 3 × 3

$$\sigma^0 = 10 \log(|DN|^2) + A$$

4-component scattering power decomposition (G4U)

Minami-Aso village



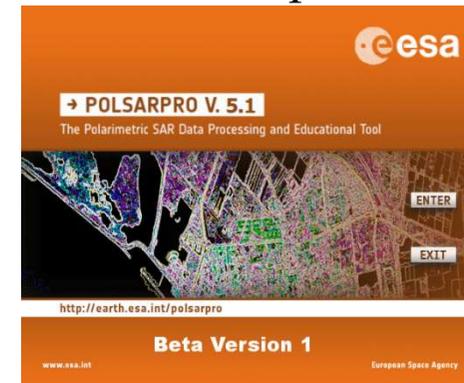
Singh et al. (2013)

$$\begin{matrix}
 \text{HH pol.} \\
 \text{HV pol.} \\
 \text{VH pol.} \\
 \text{VV pol.}
 \end{matrix}
 \begin{matrix}
 \left. \begin{matrix} \\ \\ \\ \end{matrix} \right\} \rightarrow \\
 \end{matrix}
 [S] = \begin{bmatrix} S_{HH} & S_{HV} \\ S_{VH} & S_{VV} \end{bmatrix}$$

- Surface scattering (**Ps**)
- Double-bounce scat. (**Pd**)
- Volume scattering (**Pv**)
- Helix scattering (**Pc**)

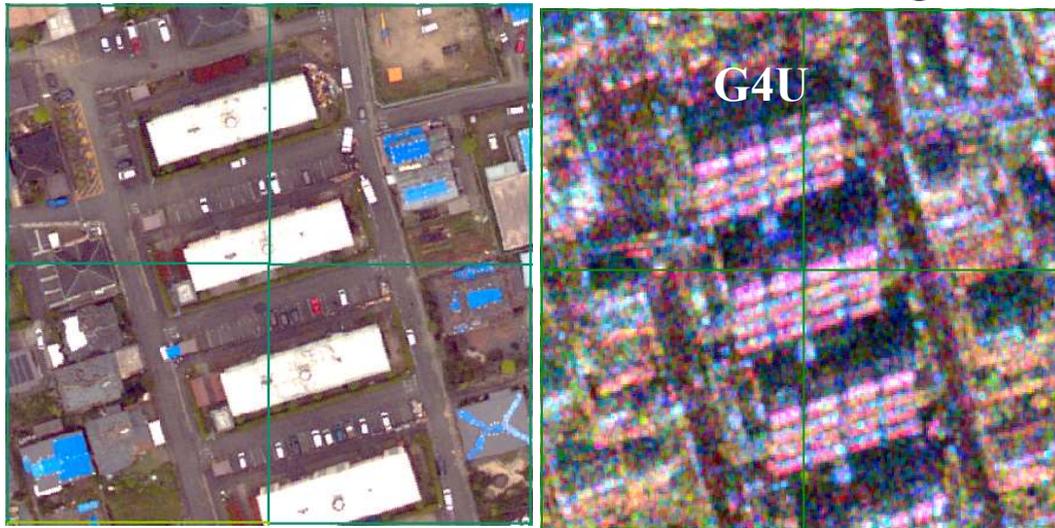


PolSAR pro 5.1

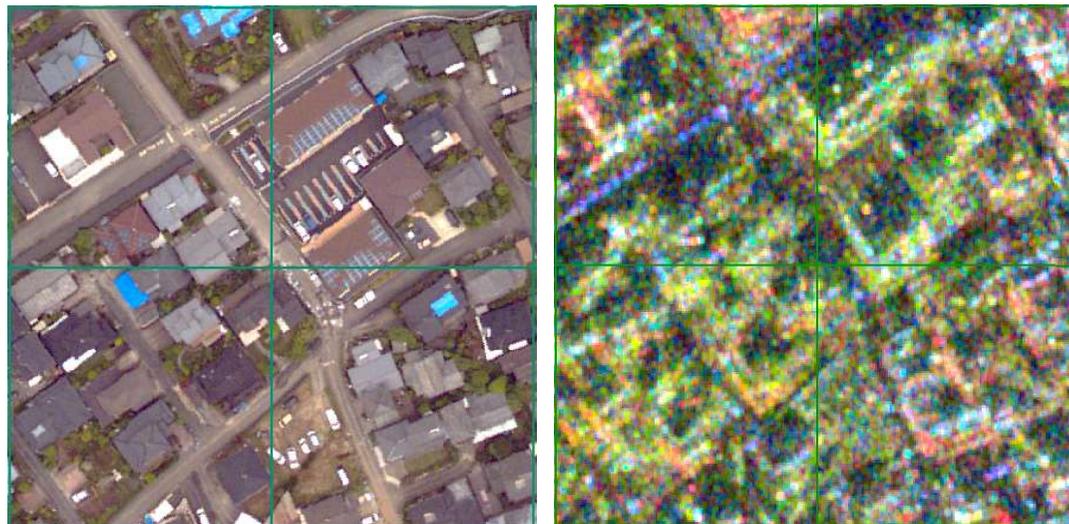


R: σ_d **G:** σ_v **B:** σ_s

Comparison of aerial photo and Pi-SAR2 color composite for low-damage areas



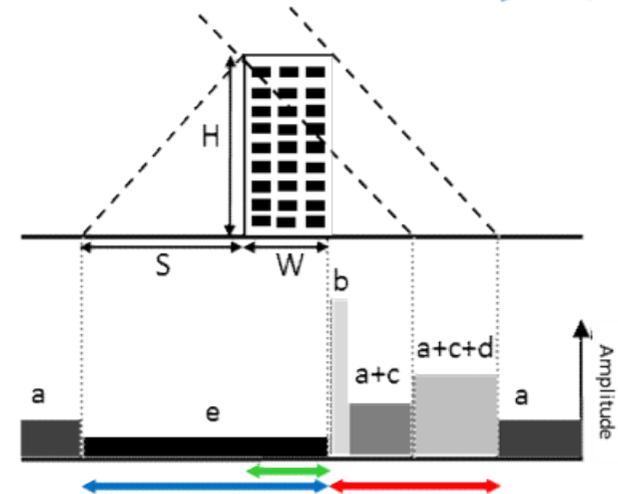
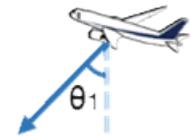
(a) Low collapsed ratio area with RC buildings



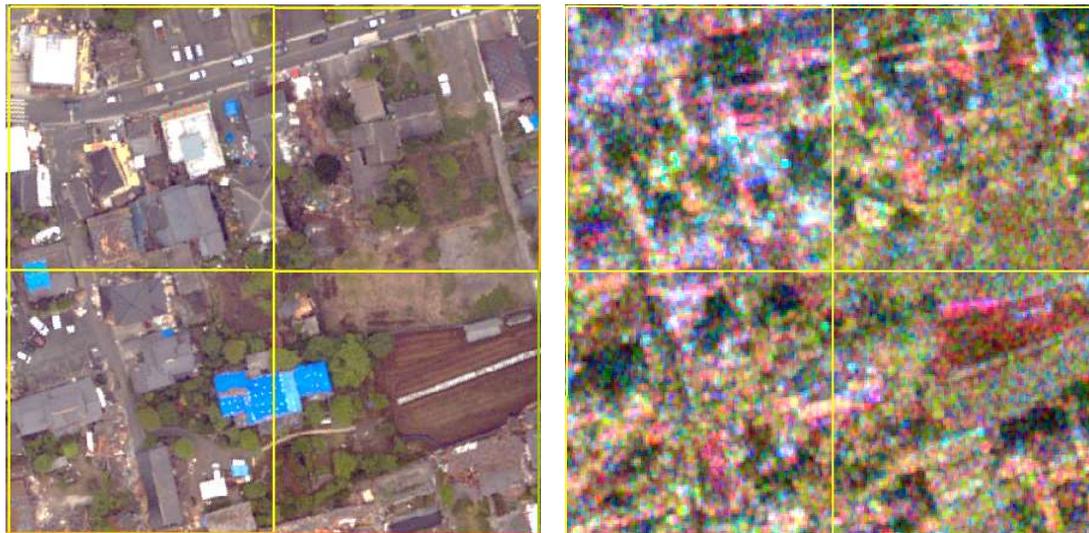
(b) Low collapsed ratio area with wooden houses



←→ Footprint
←→ Layover
←→ Radar Shadow



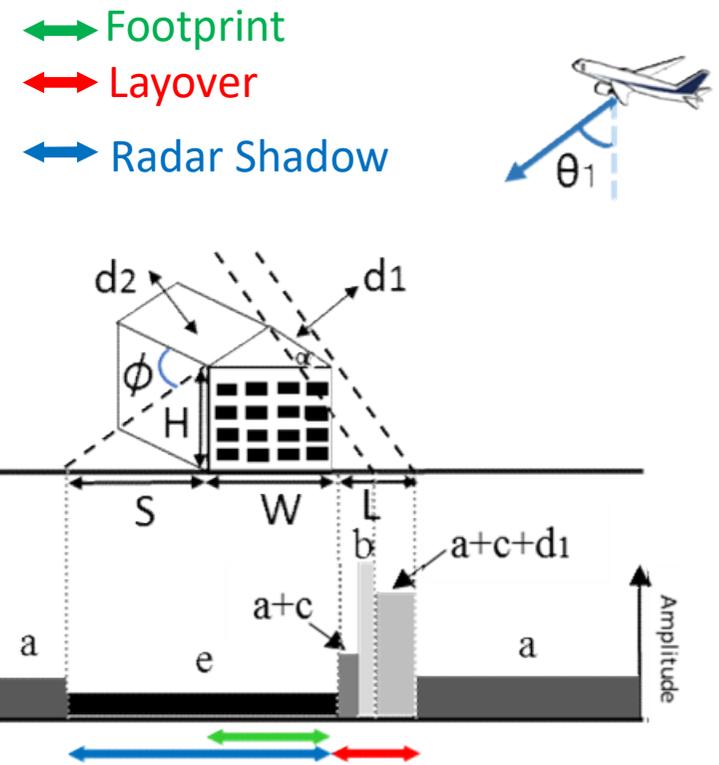
Comparison of aerial photo and Pi-SAR2 color composite (center) for high-damage areas



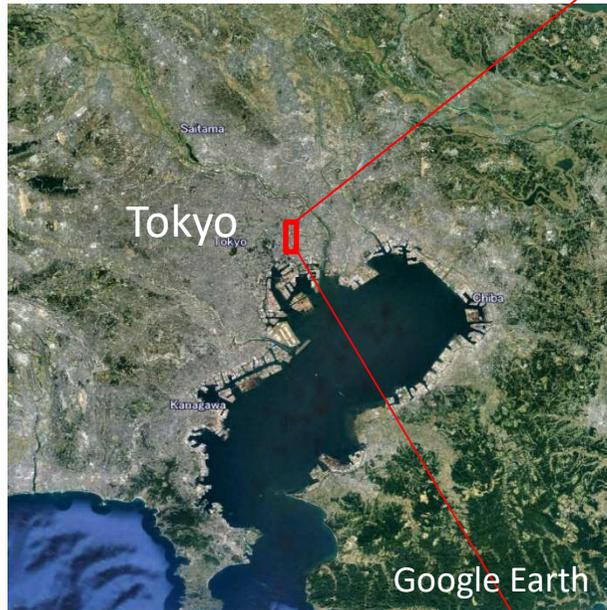
(c) high collapsed ratio area ($R_c \geq 40\%$)



(d) high collapsed ratio area ($R_c \geq 60\%$)



Airborne Pi-SAR-X2 images for bridges in central Tokyo



NICT, Japan



Polarimetric and Interferometric Airborne SAR (Pi-SAR-X2)



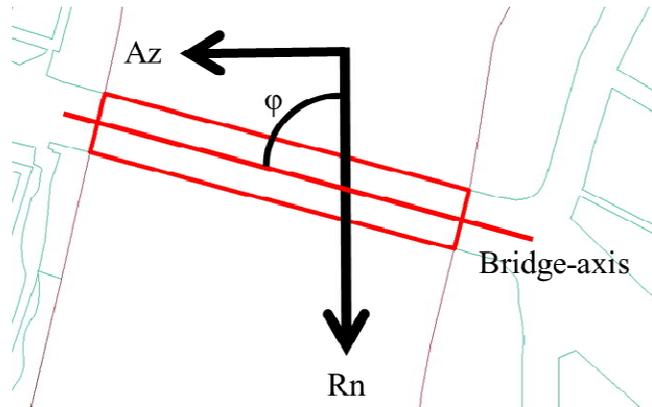
R:HH
G:HV
B:VV



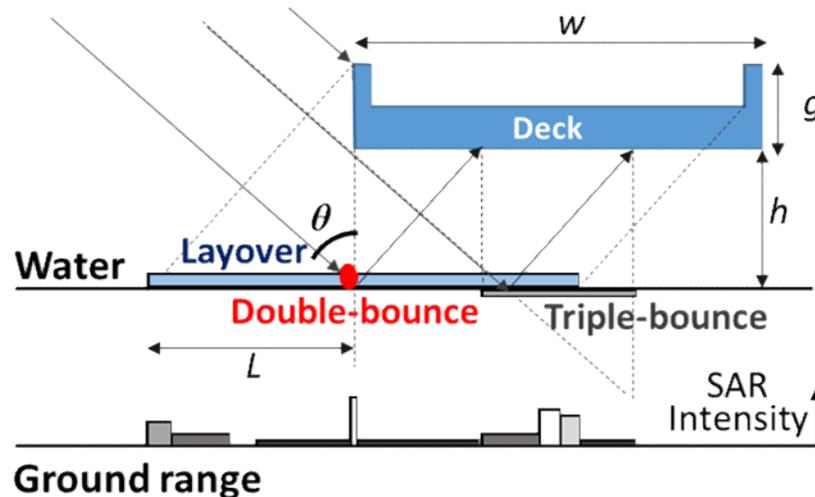
Date	22 December, 2009	10 January, 2013
Incident angle (°)	42.2 (center)	44.3 (center)
Pixel size (m)	0.25 × 0.25 (Az × Rn)	0.25 × 0.25 (Az × Rn)
Azimuth angle (°)	2.06	-90.1

Effect of illumination angle φ to the bridge axis

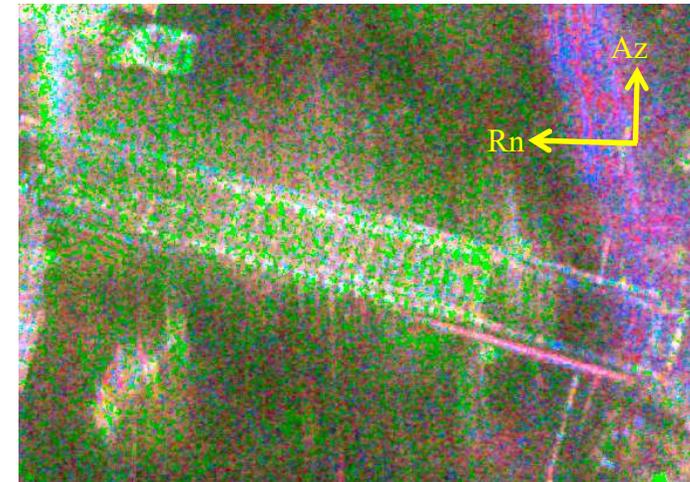
In addition to the structural types, the backscattering characteristics of bridges also change according to the illumination angle



φ : The illumination angle between the bridge-axis and the range-direction

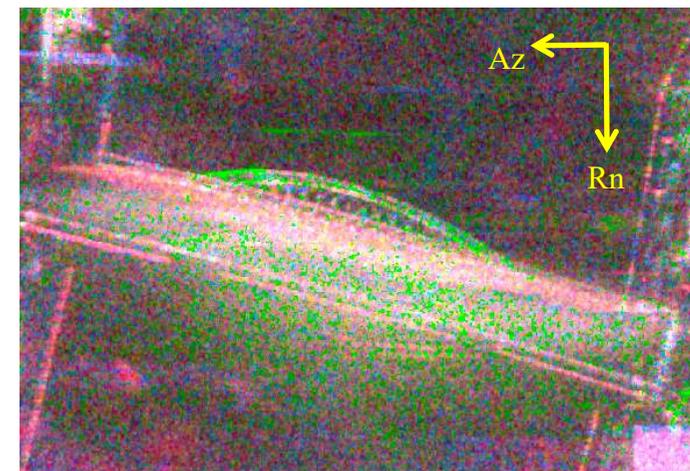


R:Pd
G:Pv
B:Ps



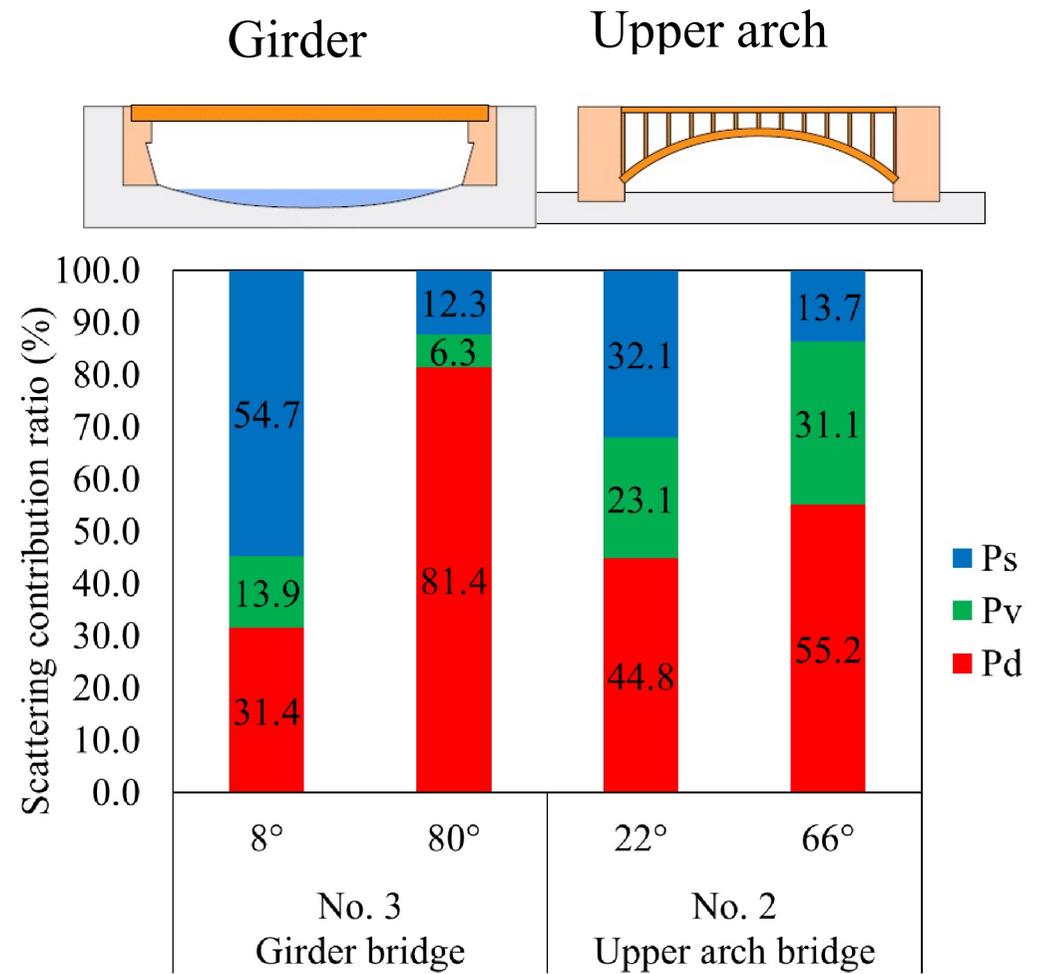
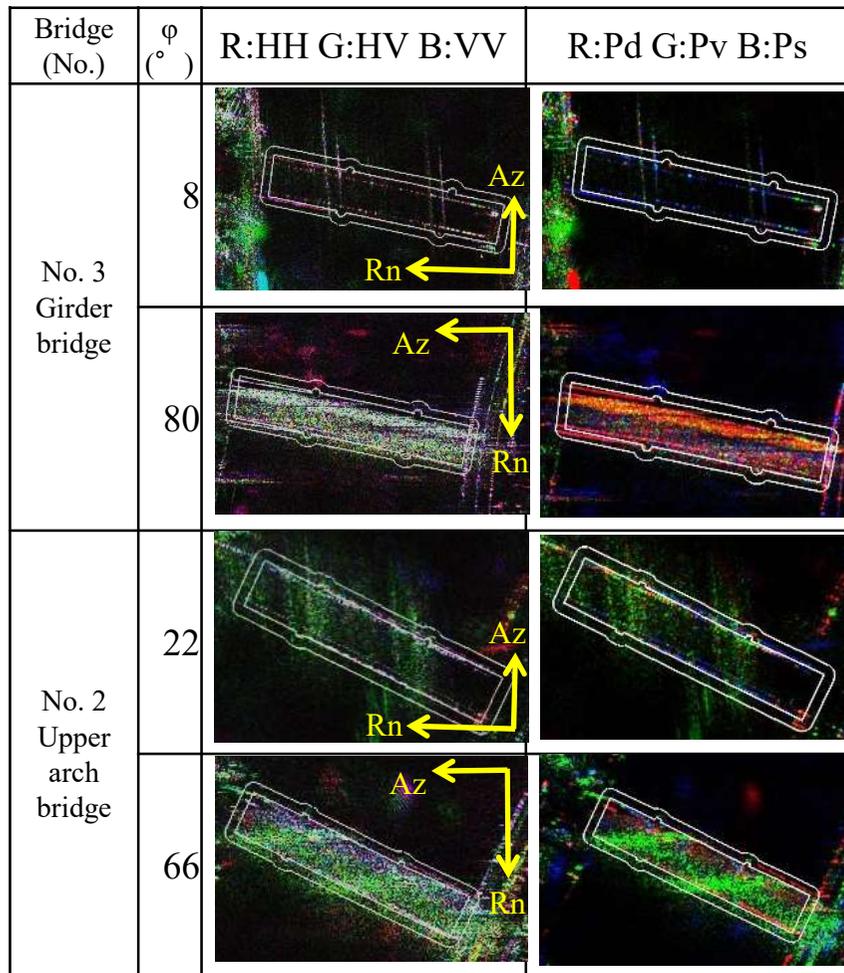
$\varphi=12^\circ$ (22 December, 2009)

R:Pd
G:Pv
B:Ps



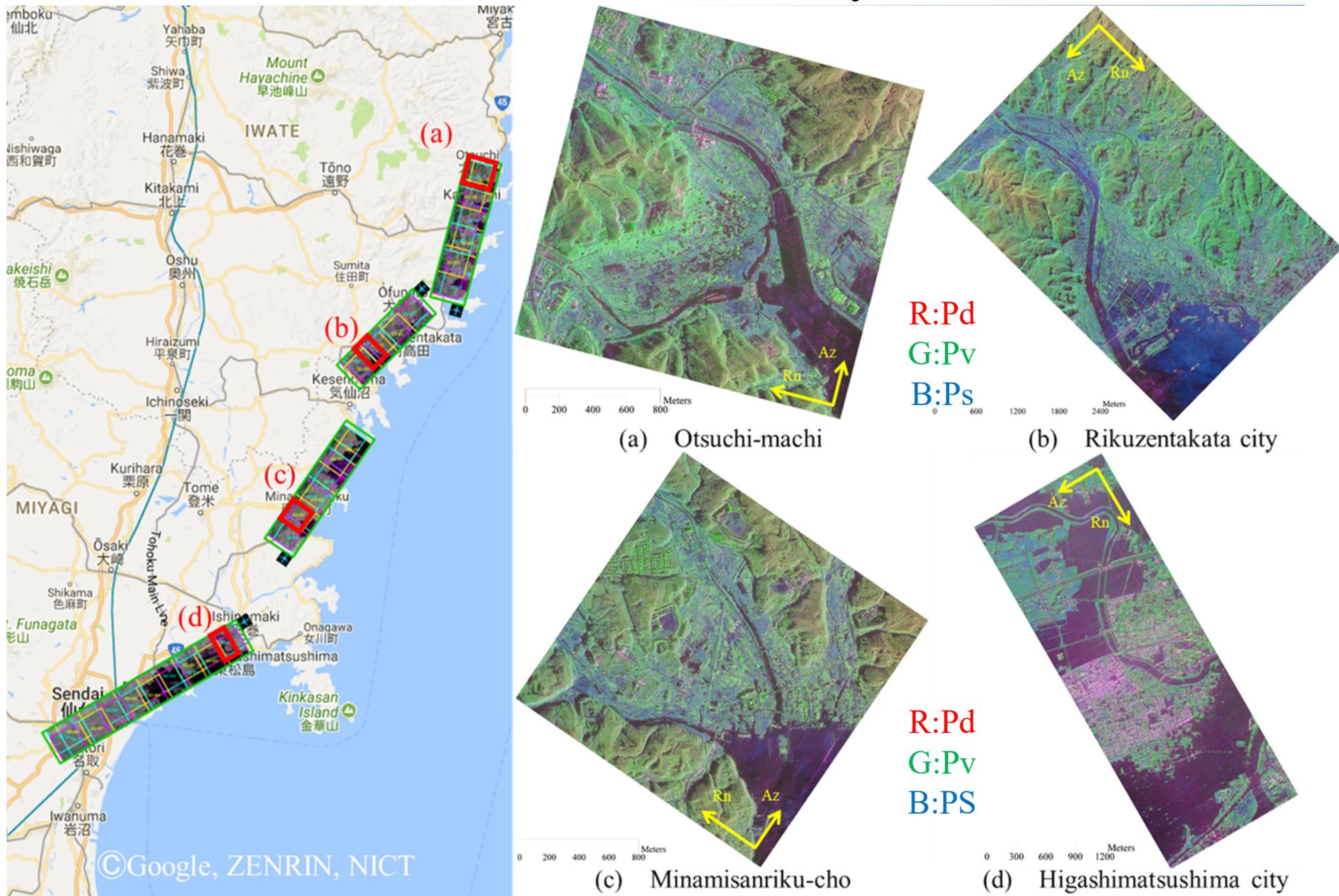
$\varphi=76^\circ$ (10 January, 2013)

Pi-SAR-X2 images of Girder bridge and Upper-arch bridge

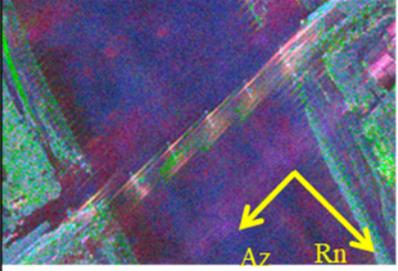
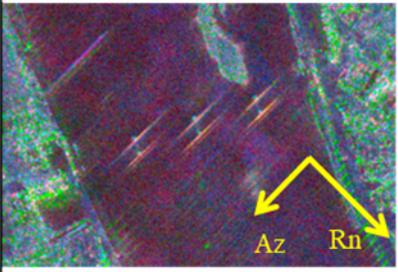


- Girder bridge : $\varphi \rightarrow 90^{\circ}$ Pd ↑ Ps ↓
- Upper arch : $\varphi \rightarrow 90^{\circ}$ Pd ↑ Ps ↓

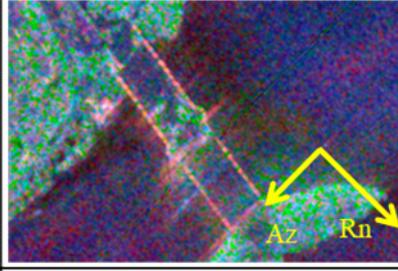
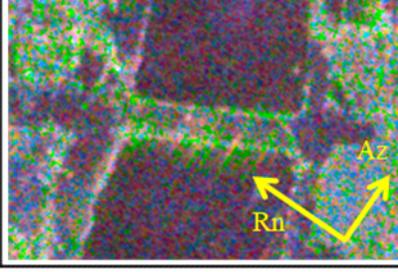
Pi-SAR-X2 data used in this study



Washed away

No.	R:Pd G:Pv B:Ps (Sigma naught)	Google Earth Before	GSI map Soon after
101			
103			

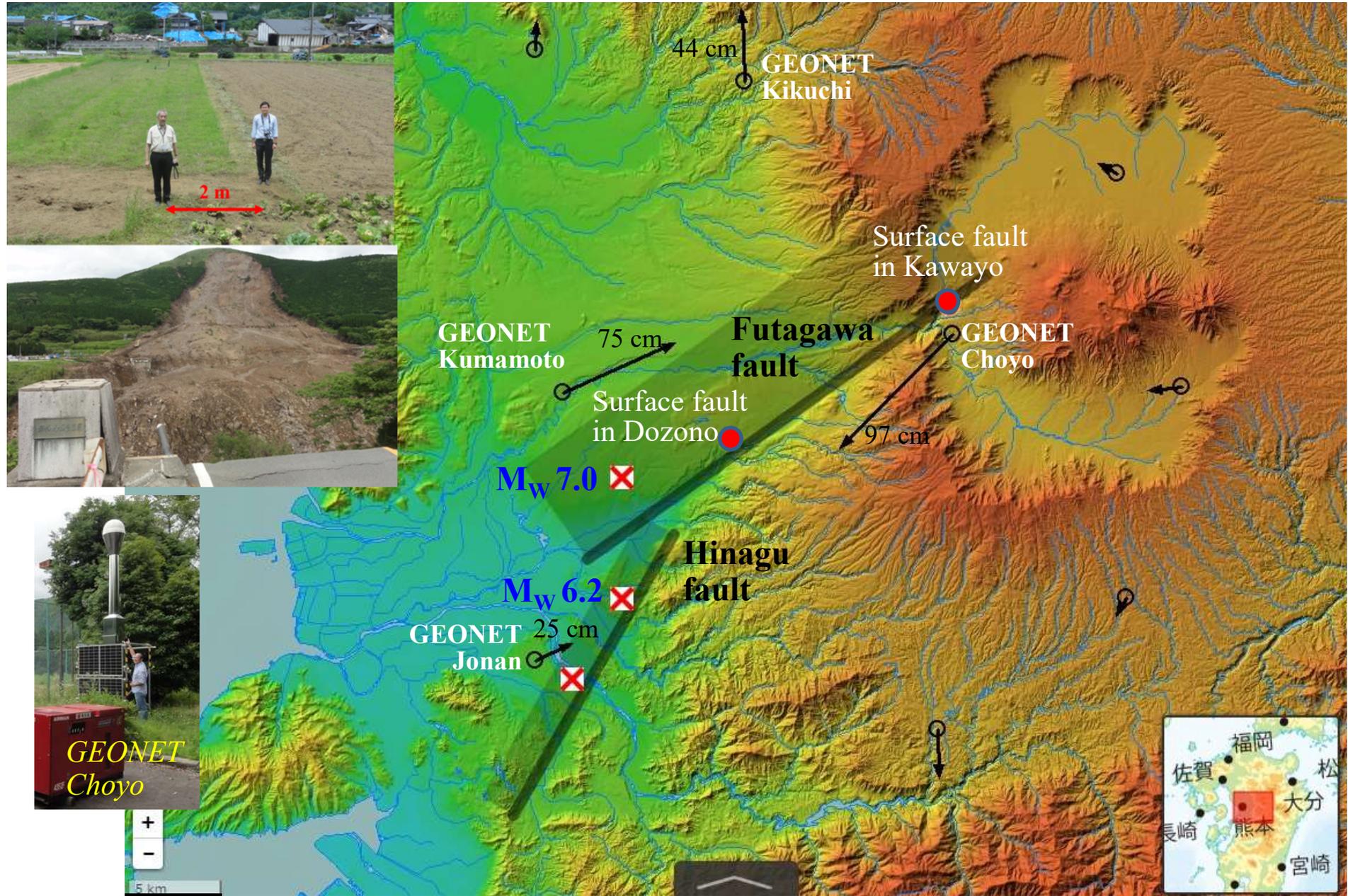
Survived
with debris

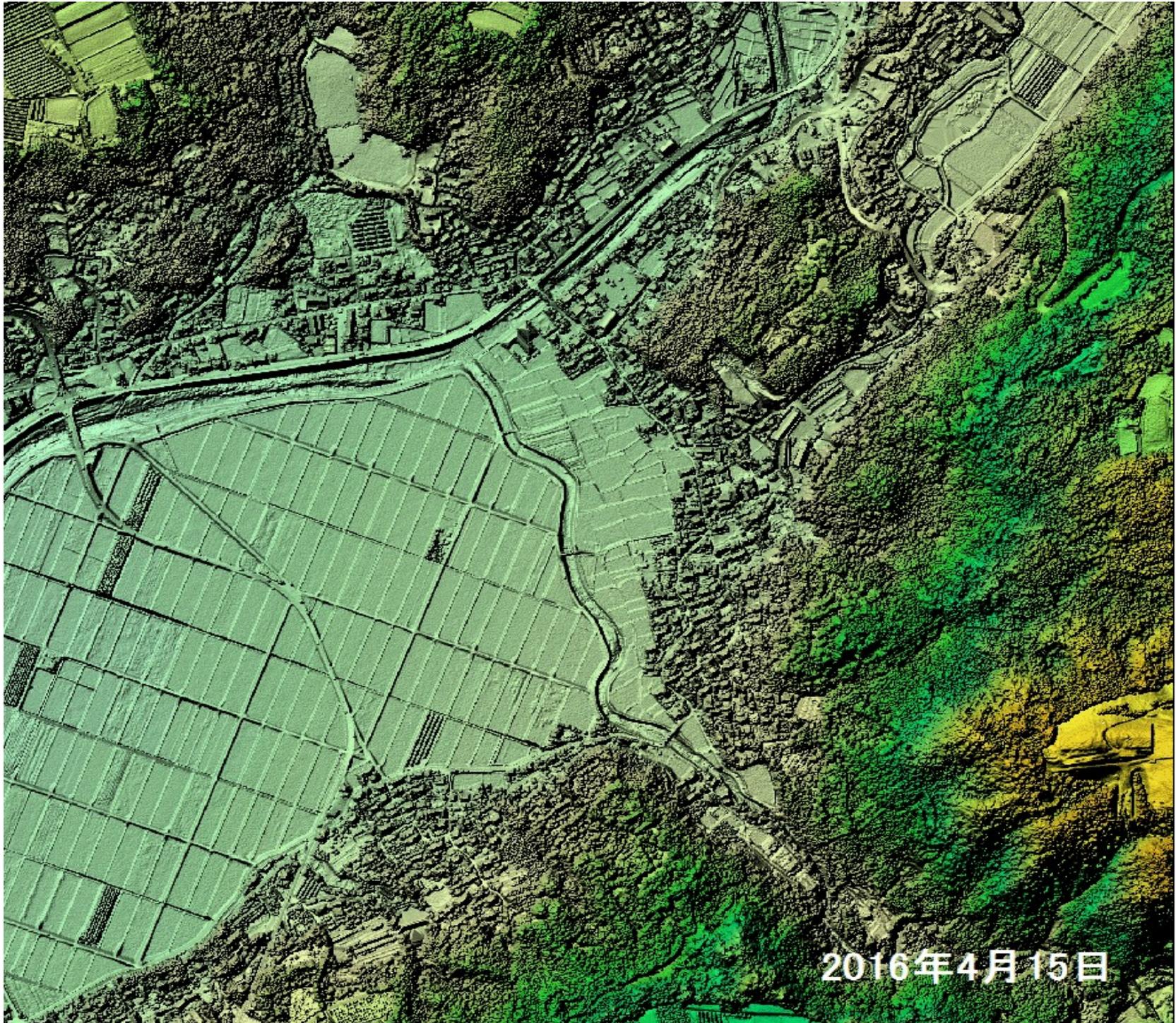
No.	R:Pd G:Pv B:Ps (Sigma naught)	Google Earth Before	GSI map Soon after
96			
124			

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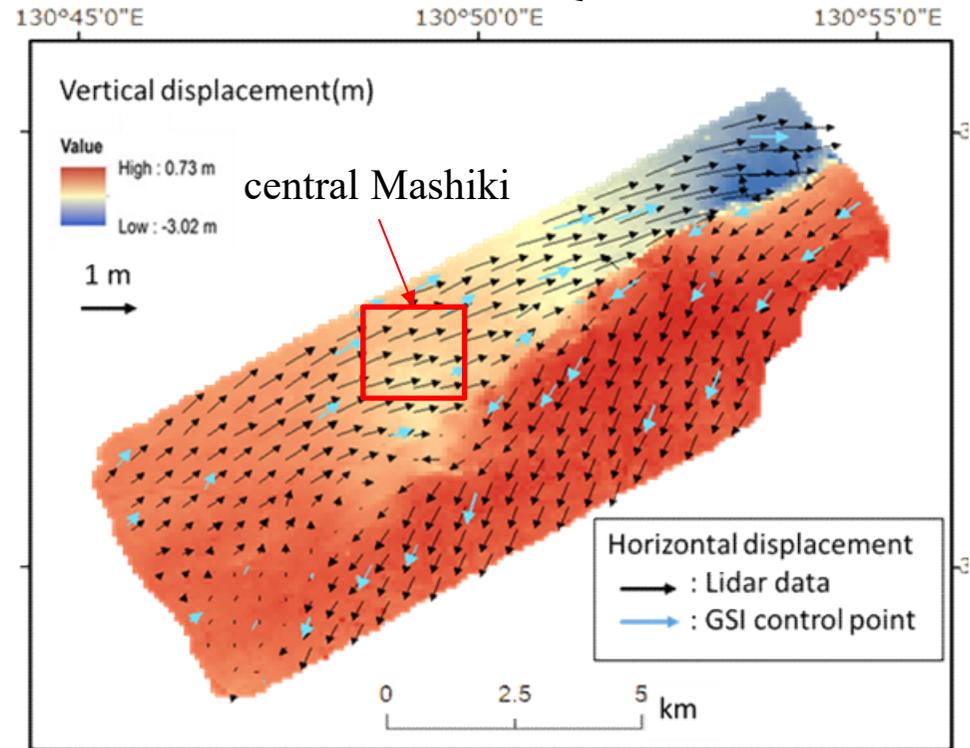
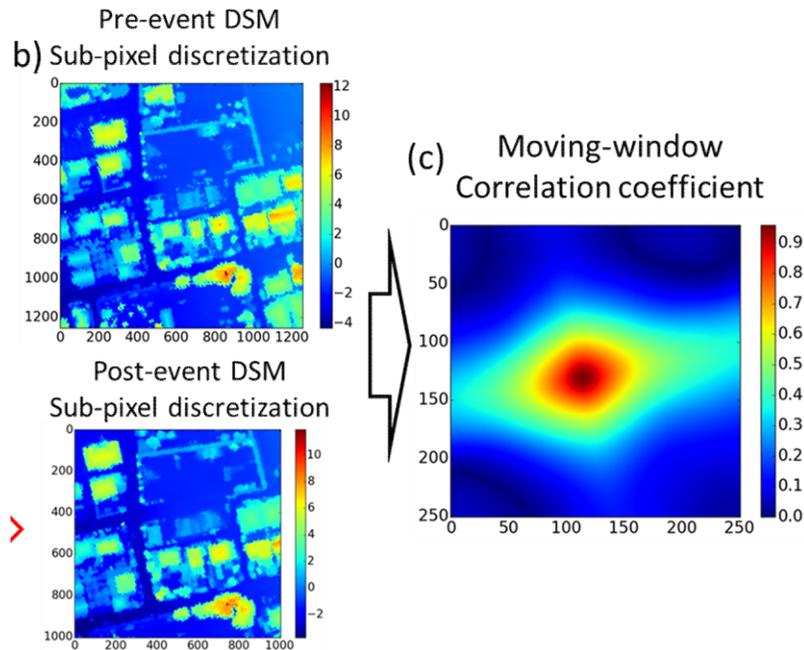
Epicenters, faults, and GPS stations in the 2016 Kumamoto EQ



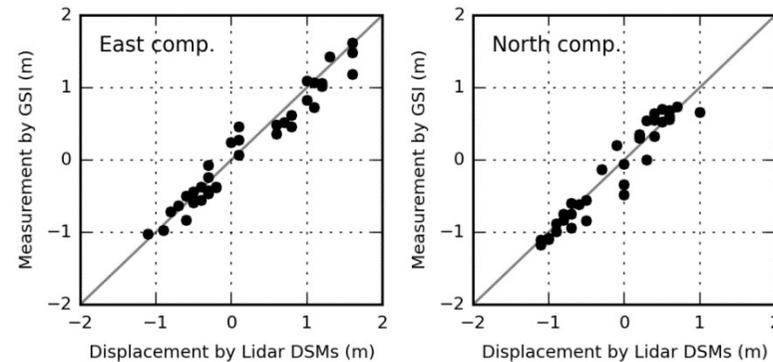


2016年4月15日

Estimation of 3D coseismic displacement from LiDAR DSMs in the main-shock of the Kumamoto EQ

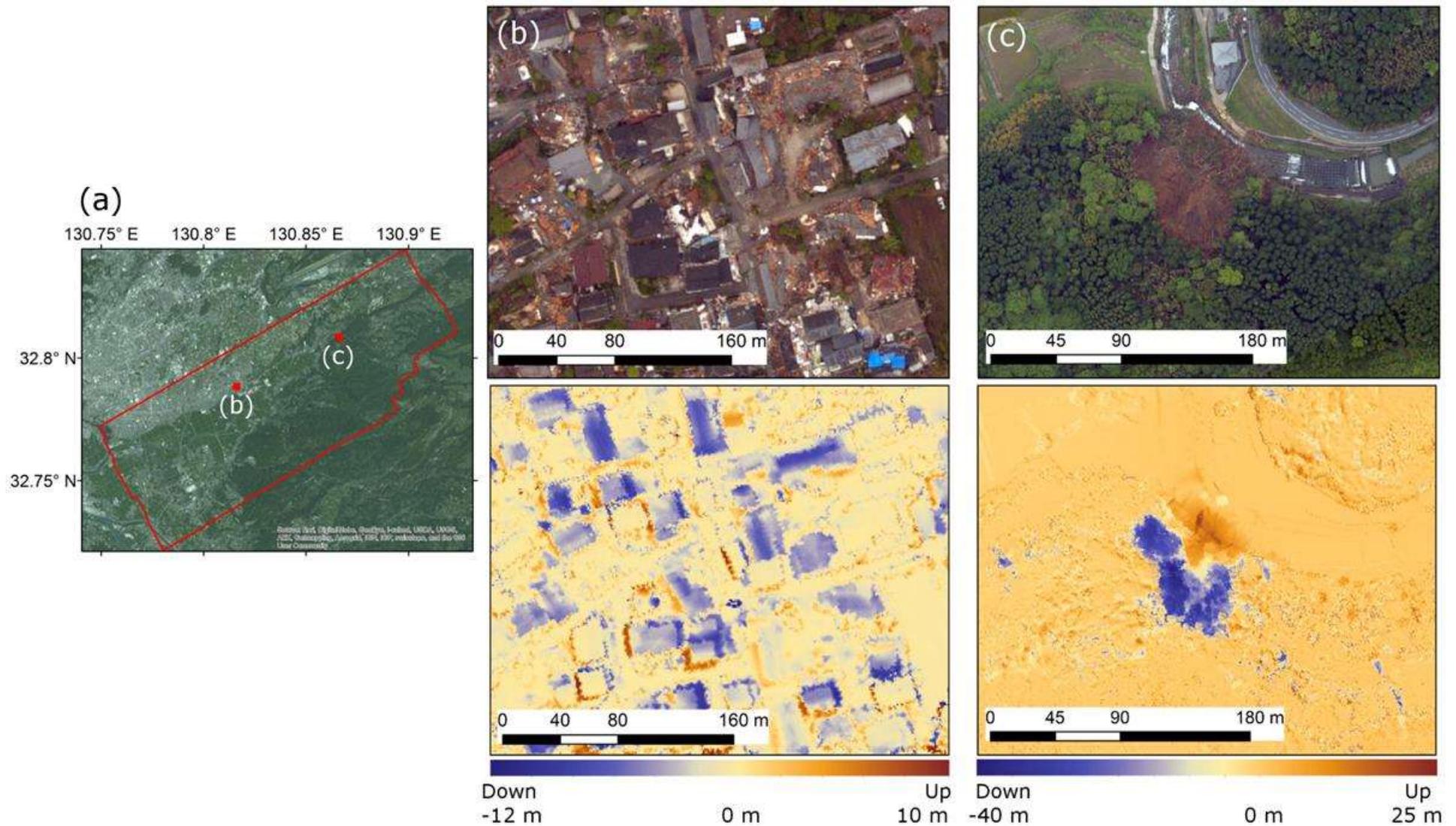


Maximum cross-correlation to determine crustal movements from LiDAR DSMs
By 100 m grid cells



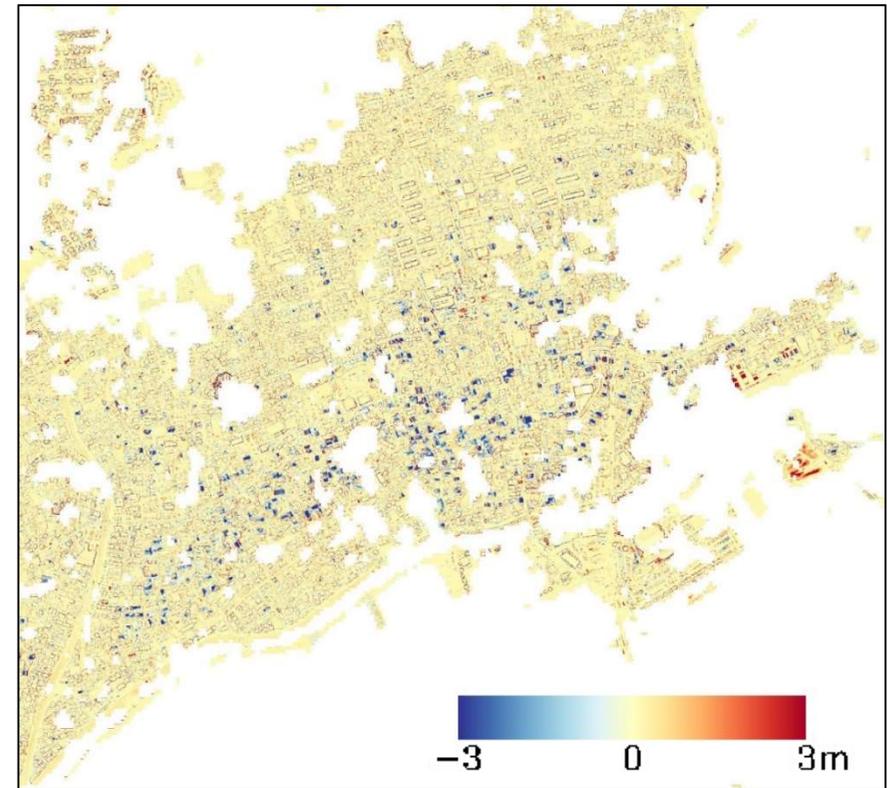
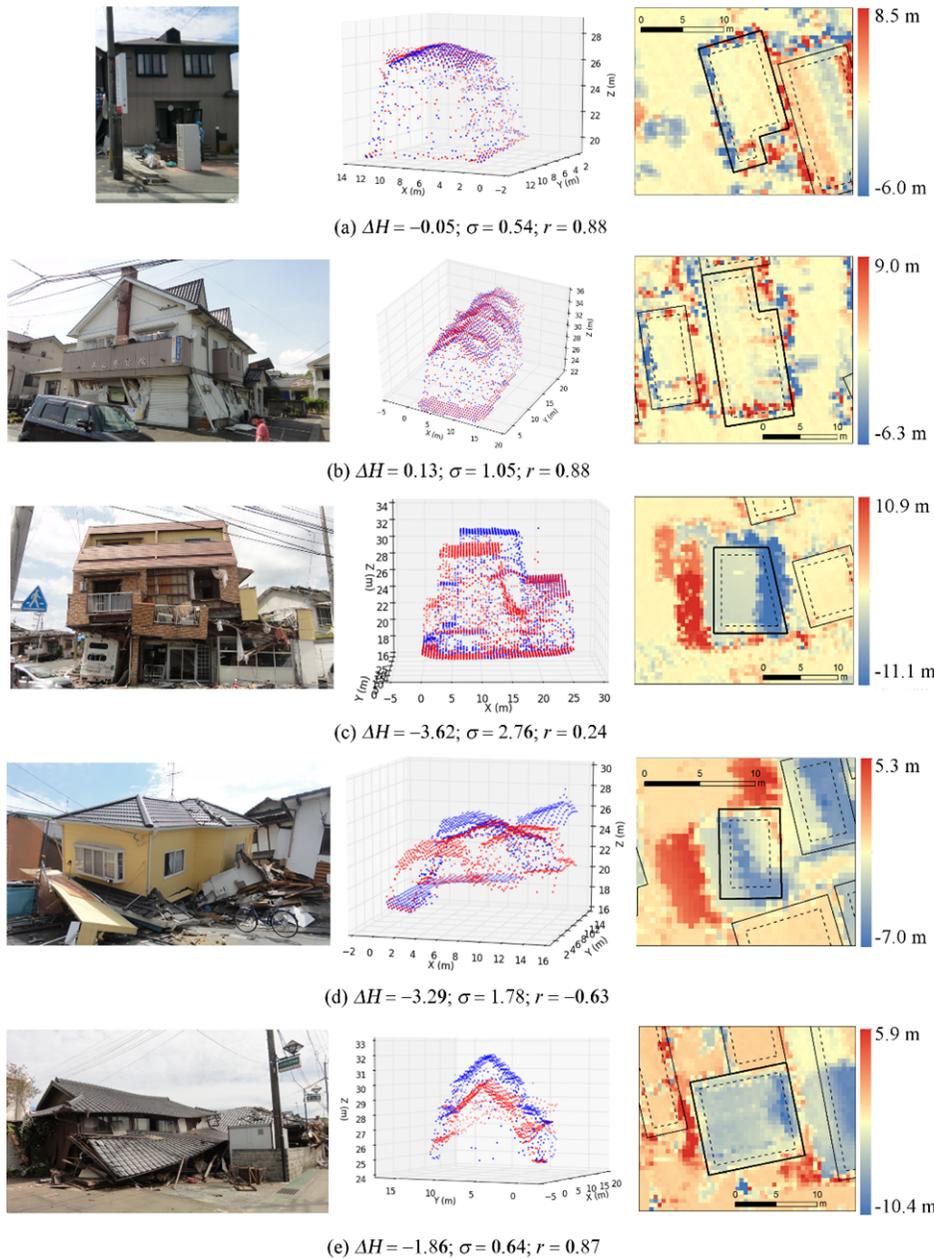
Moya, L., Yamazaki, F., Liu, W., and Chiba, T.: Calculation of coseismic displacement from lidar data in the 2016 Kumamoto, Japan, earthquake, *Nat. Hazards Earth Syst. Sci.* 17, 143-156, 2017

Extraction of collapsed buildings and landslide by the difference of LiDAR Digital Surface Models (DSMs)



F. Yamazaki, W. Liu, Remote sensing technologies for post-earthquake damage assessment: A case study on the 2016 Kumamoto earthquake, 6th Asia Conference on Earthquake Engineering, 2016.

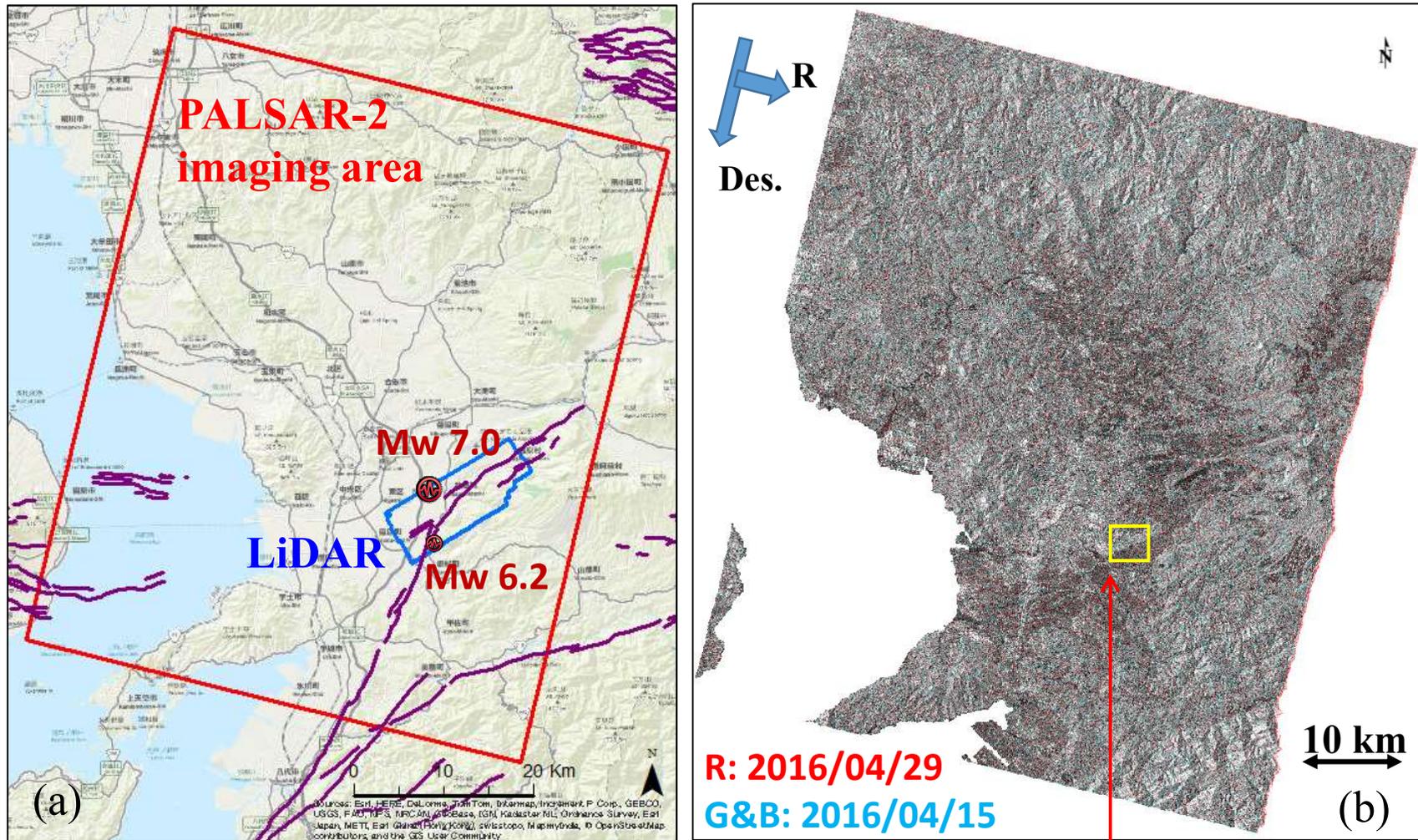
Extraction of collapsed buildings using two DSMs' height difference after removing crustal movements



Difference of the two DSMs

L. Moya, F. Yamazaki, W. Liu, M. Yamada, Detection of collapsed buildings from lidar data due to the 2016 Kumamoto earthquake in Japan, NHESS, 2018.

Location (a) and color-composite (b) of ALOS-2 PALSAR-2 images



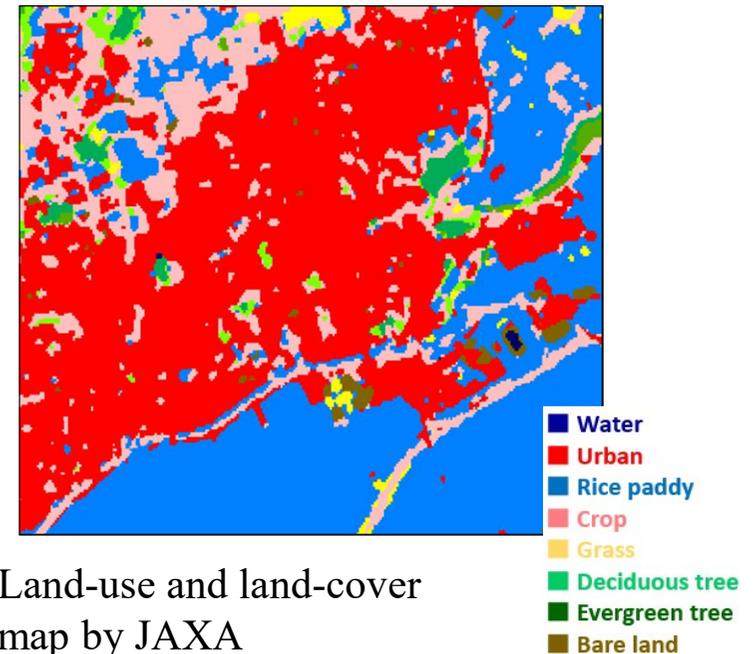
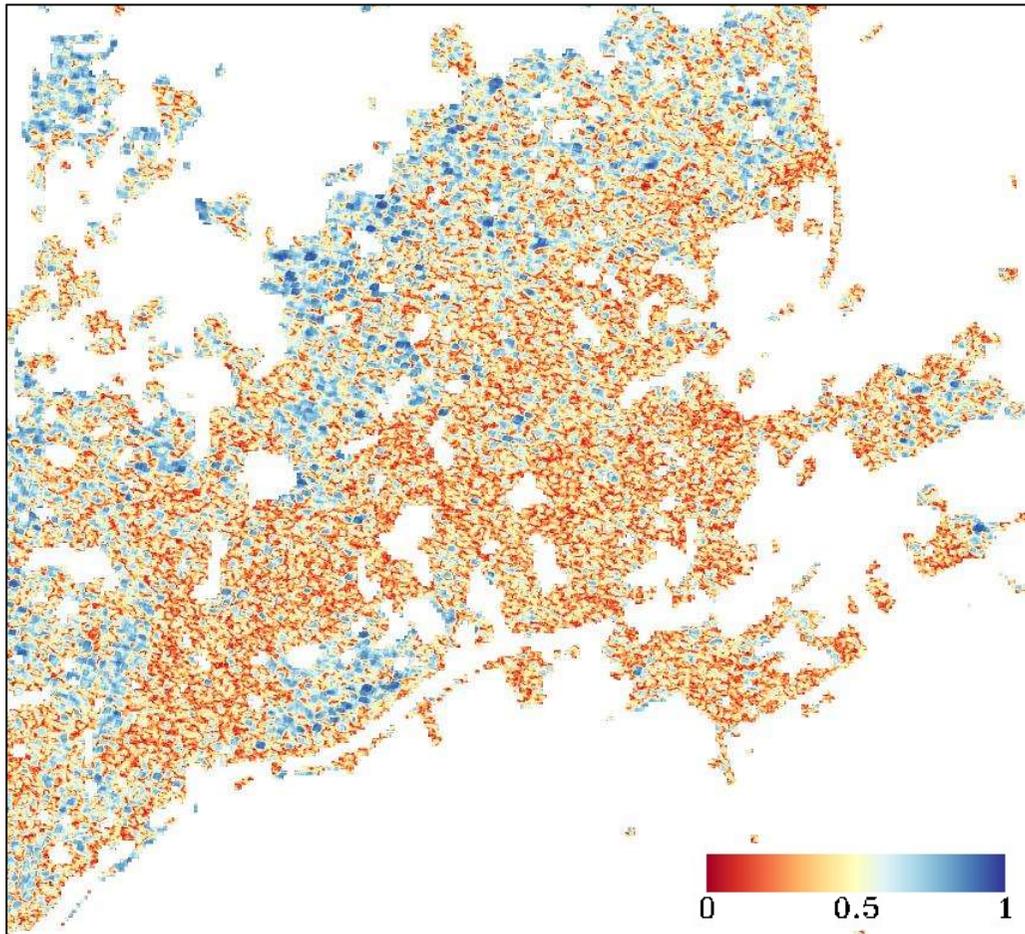
Pre-event: 2016/04/15 **Post-event: 2016/04/29**

Off-nadir angle: 32.4° , Mode: StripMap, Polarization: HH

Resolution: 1.43 m (range) and 1.74 m (azimuth)

the target area in Mashiki town

Coherence between the two PALSAR-2 images (2016/4/15 vs 2016/4/29) for the urban land-cover in the central Mashiki Town

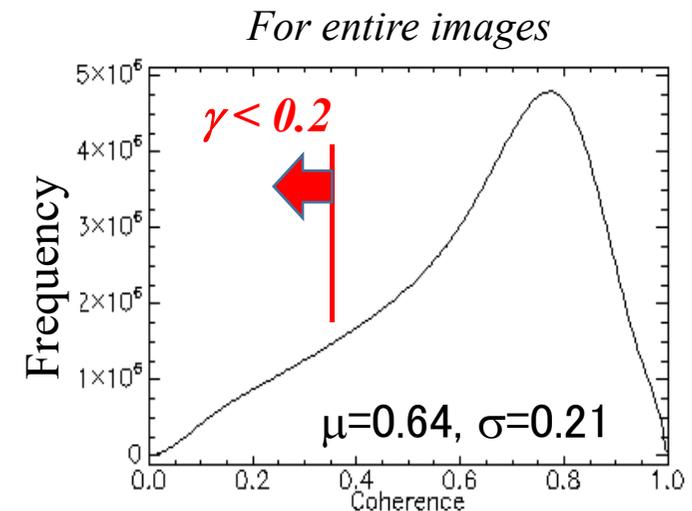


Land-use and land-cover map by JAXA

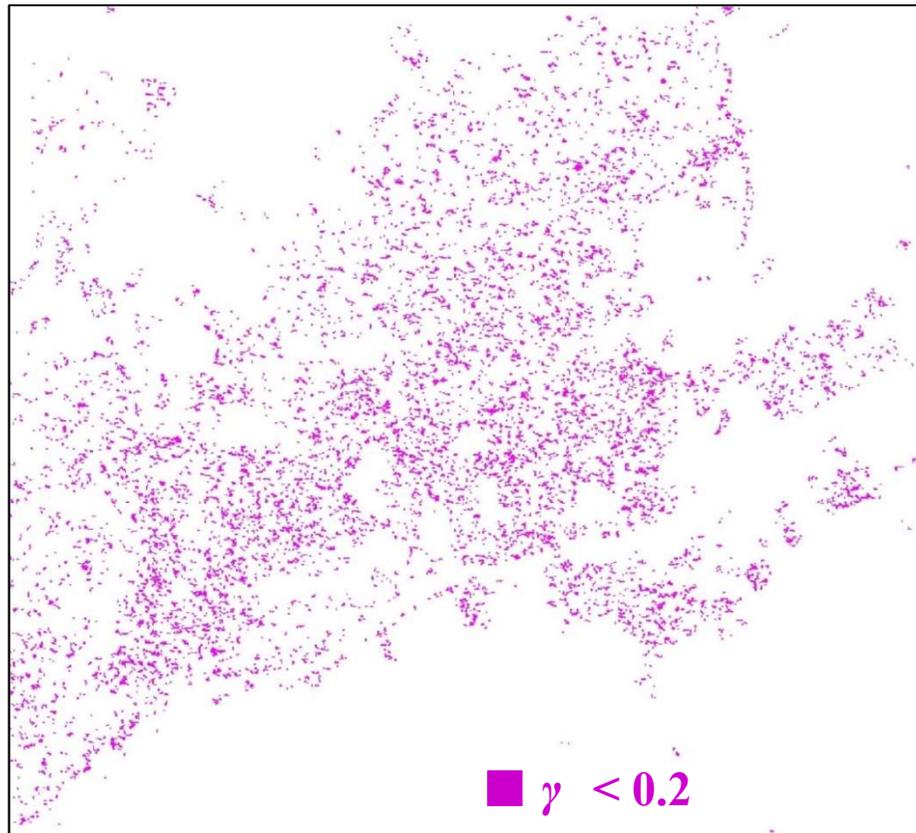
Coherence

$$\gamma = \frac{\sum C_1 C_2}{\sqrt{\sum |C_1|^2} \sqrt{\sum |C_2|^2}}$$

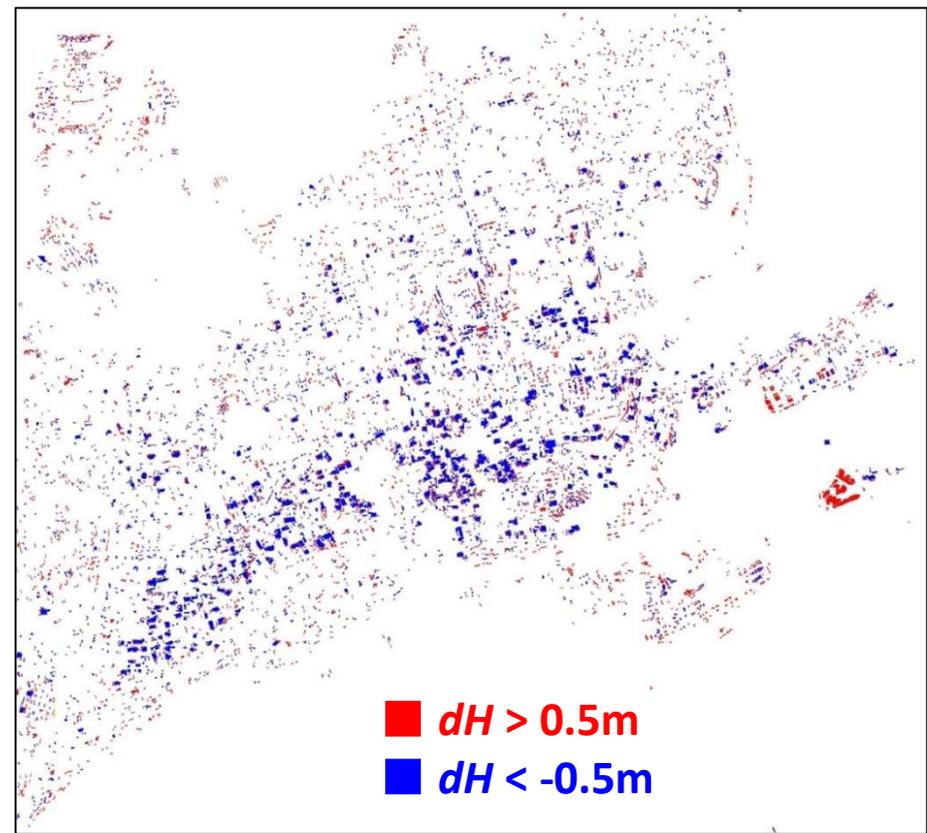
C is a complex number with phase (ϕ) and magnitude (A)



Extraction of changrd areas by coherence and height-difference



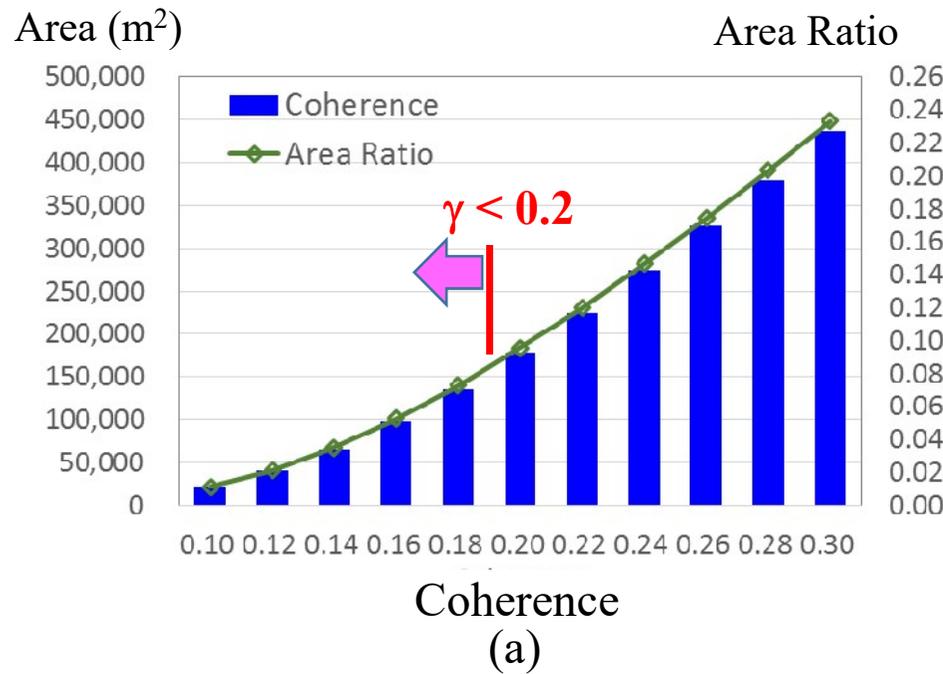
Areas extracted by
low coherence ($\gamma < 0.2$)



Areas extracted by DSM
difference: $|dH| > 0.5$ m

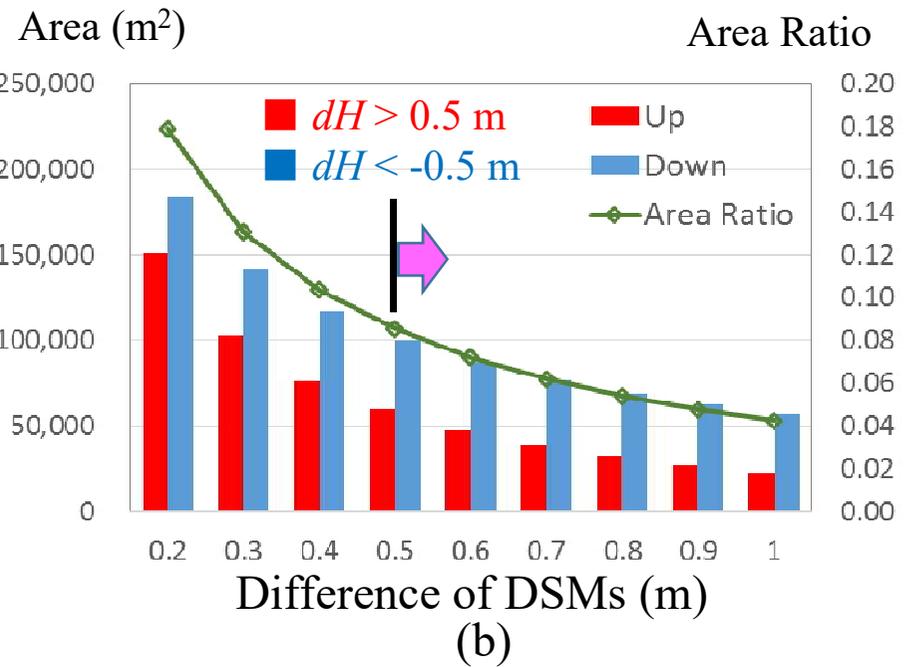
Coherence and the extracted area by the coherence threshold

*the extracted area
= about 9 %*



Height difference and the area exceeding \pm the thresholds

*the extracted area
= about 8.5 %*



Drone (UAV) flight in Onagawa on Nov. 14, 2014



March 19, 2011 by GSI



Phantom2 vision+ 2014.11.14

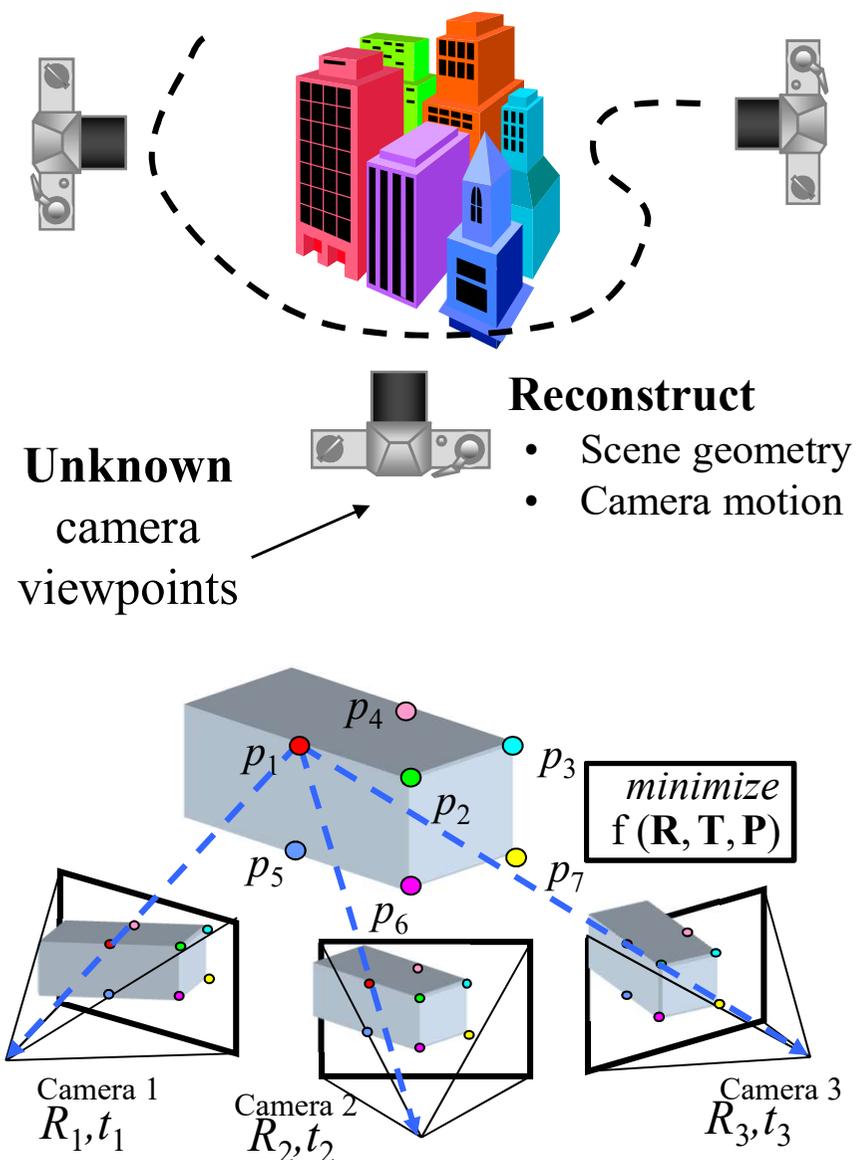
H= 30 m



Building B



Structure from Motion (SfM) and Developed 3D Model



- Construction of 3D model of structures from many images with unknown positions.
- Combination of
 - Computer Vision -- 3D modeling
 - Robot Vision -- camera position

Agisoft PhotoScan



F. Yamazaki, T. Matsuda, S. Denda, W. Liu Construction of 3D models of buildings damaged by earthquakes using UAV aerial images,, 9th Pacific Conference on Earthquake Engineering, Sydney, 2015.

Summary

- **Application of remote sensing** technologies to **disaster response** was discussed based on real earthquake events.
- **Optical satellite** images were used to observe **floods, landslides,** and damages to **built environment**. The **improvement of resolution** enabled us to monitor small-scale damages.
- **Thermal** satellite sensor could extract **flooded areas** as well as bush fires and volcanic activities.
- **Satellite SAR** sensors were used to extract **various damage situation**, even at night and under cloud-cover conditions.
- **Airborne SAR** can be used for detailed land-cover and damage mapping.
- **Aerial surveys** by airplanes and **drones** were carried out to observe detailed damage situations. **LiDAR** is also promising to observe the ground-surface situations.

Thank you very much!

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